



Development of an “iTomography” infrastructure for non-destructive documentation of cultural heritage objects



[Georgios Karagiannis](#),

Electrical Eng. PhD

«ORMYLIA» Foundation, Scientific Head

e-mail: g.karagiannis@artdiagnosis.gr,

g.karagiannis@teemail.gr



Outline

- Introduction
- Mechanical Scaffold - Support
- Instrumentation and Software Development
 - Device – Technique Inventory - Toolbox
 - Acquisition Software
 - Registration Procedure and Algorithms
- Measurements and Data Registration
 - Case studies – Cultural Heritage Objects
 - **Combination/ Fusion of the data –**
(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ...
“i” Tomography - iTomography (To be presented in IEEE IST 2018)



Introduction

“ORMYLIA” Foundation mobile Lab NDT methods used for the acquisition of the “tomographic” information

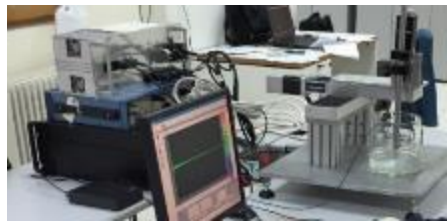


*Infrared imaging from $1\mu\text{m}$ to $5\mu\text{m}$ and thermal imaging form $3\text{-}5\mu\text{m}$
(XENICS FPA 640×480 elements)*

*Raman and micro Raman spectroscopy with 1064nm of laser source
(BWTEK portable Raman spectroscope)*

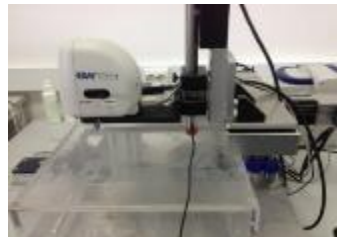


*Infrared spectroscopy in various modes (Reflectance, Transmittance-Absorbance and ATR) with and without the use of optical fibers
(2 BRUKER OPTICS FTIR systems one IR-CUBE, one ALPHA)*



Acoustic Ultrasonic tomography from μm to cm level of display

(2 custom made acoustic microscopy tomographs based on Olympus-xPanametrics equipment parts, 1 medical operating in lower frequencies)



*XYZ Scanners (CNC) or robotic devices with step resolution of 0.5 and $1\mu\text{m}$ with the capability to mount all the above mentioned modalities or their remote probes (XRF modality is still not fully integrated)
(The scanners-stages are provided by AEROTECH)*



Introduction

Objective

- Identification of the material and structural composition of an cultural heritage artwork (tomography with various excitations...)

Implementation

- Utilization of techniques from physics, chemistry and engineering, such as IR, UV/VIS, Ultrasound and XRF

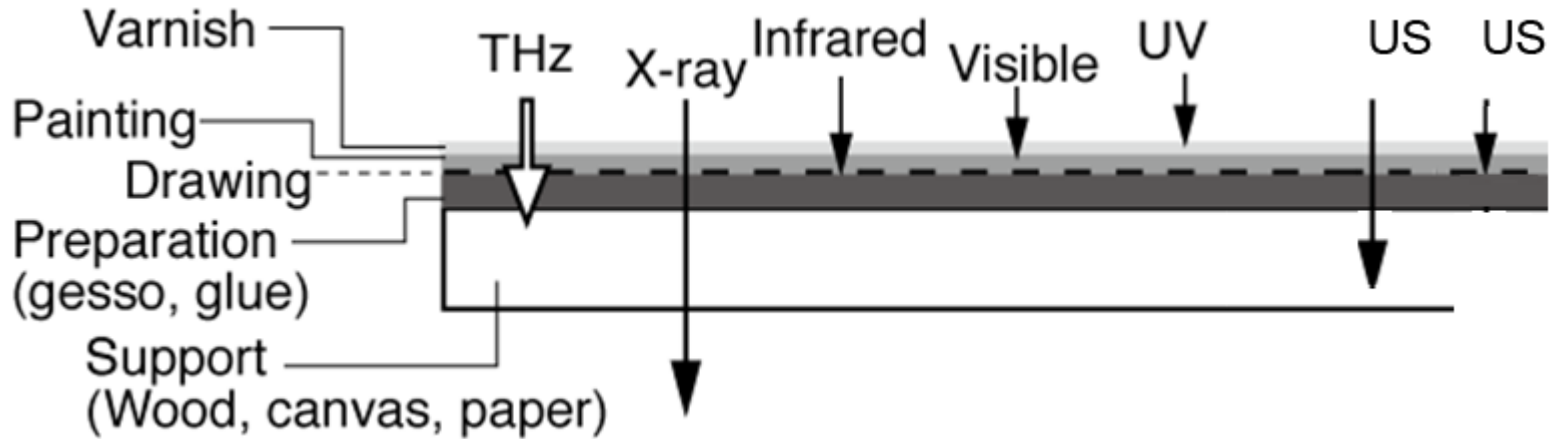
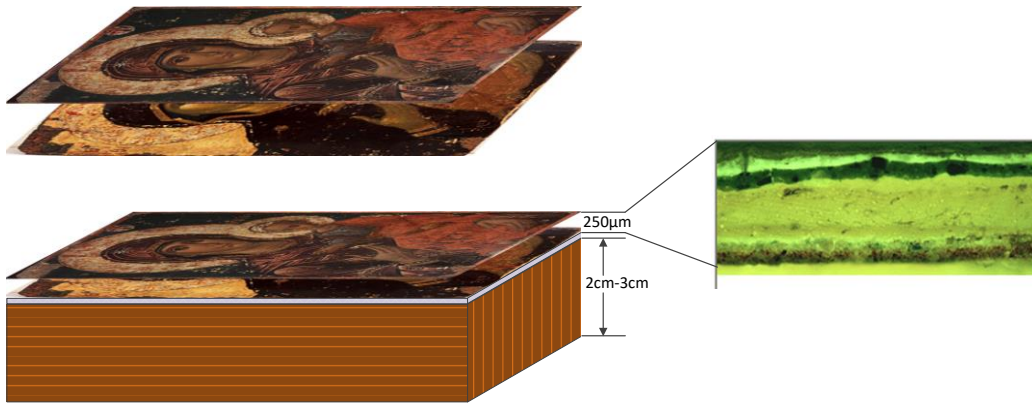
Challenge

- Design of an autonomous, unified system that combines mechanical manipulation, multimodal, non-destructive scanning and efficient image post-processing

**Integrated platform for the non-destructive
evaluation of artworks**

Introduction

Higher penetration depths are needed for the documentation of art objects serving also reconstruction non invasive.



Mechanical Scaffold - Support



- Multiple modalities active at the same time
- 6 degrees of freedom of movement of the various modalities
- Robotic XYZ $\Theta\Phi$ directions positioning system
- Coarse positioning allow different objects to be easily positioned
- Fine positioning includes 3 linear and 2 two rotation stages
 - Linear stages
 - Accuracy $\pm 1\mu\text{m}$
 - Rotation stages
 - Accuracy 3 arcmin
 - Repeatability 12 arcsec

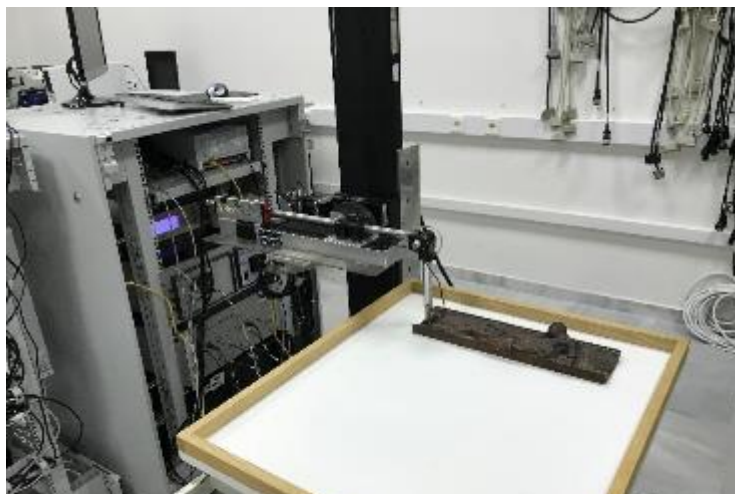
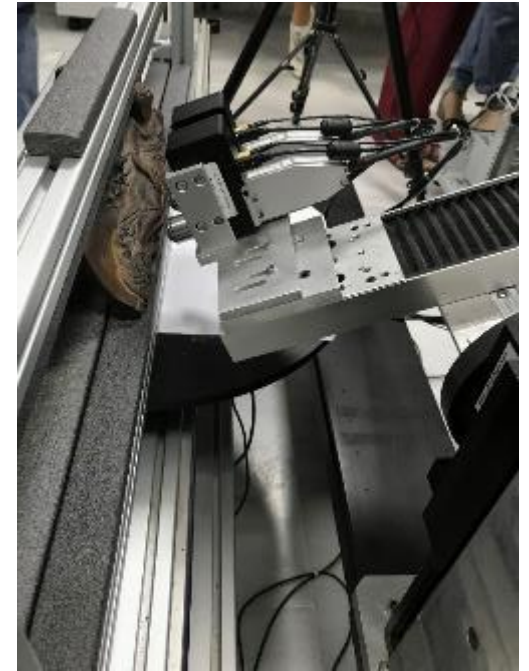
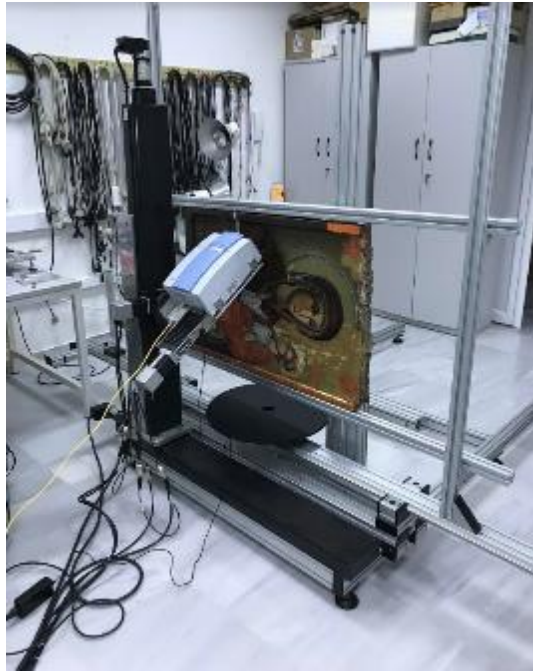
Mechanical Scaffold - Support



The platform on which the modalities are affixed is mounted on the pitch rotary stage while the yaw is performed by the stage on which the artwork is placed



Mechanical Scaffold - Support





Device - Technique Inventory - Toolbox

Principles, Conventional Ultrasound

Acquisition of a-c scan data from the multilayered structure using ultrasound frequencies of the order of **1-15MHz**, Resolution of the order of **millimeters**.

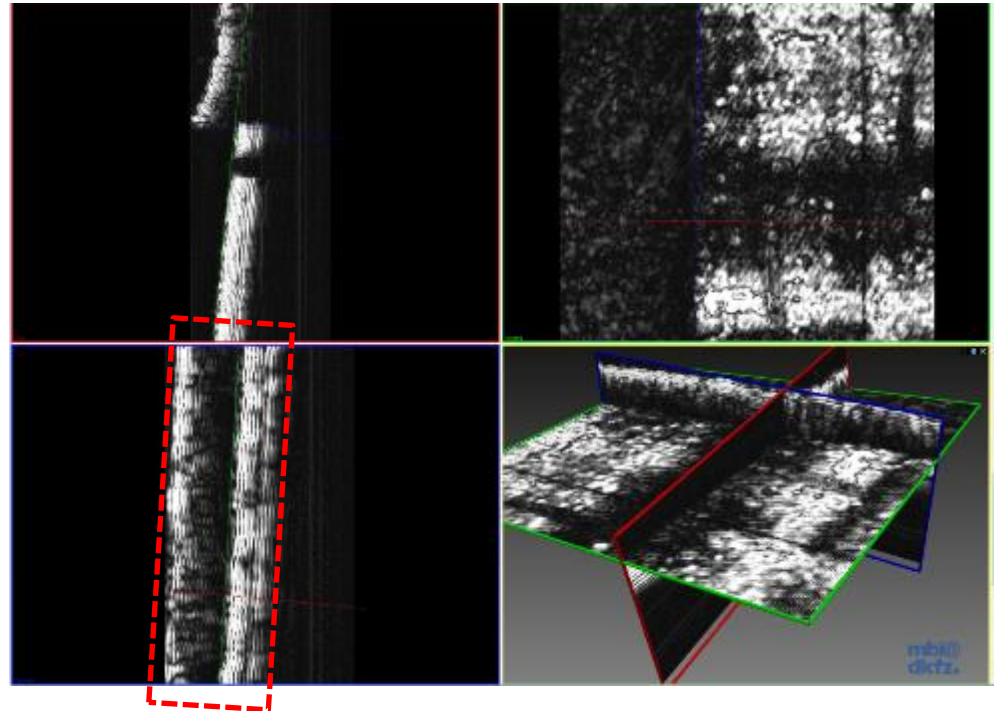
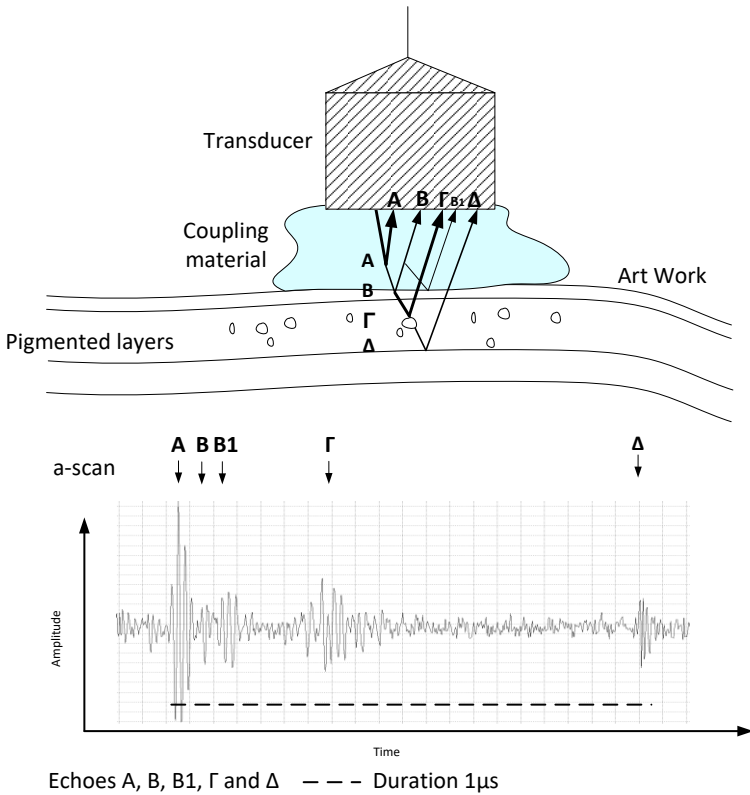
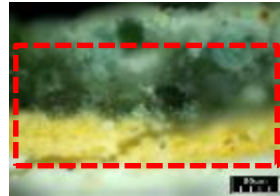


Device - Technique Inventory - Toolbox

Principles, High frequency Ultrasounds, Acoustic Microscopy

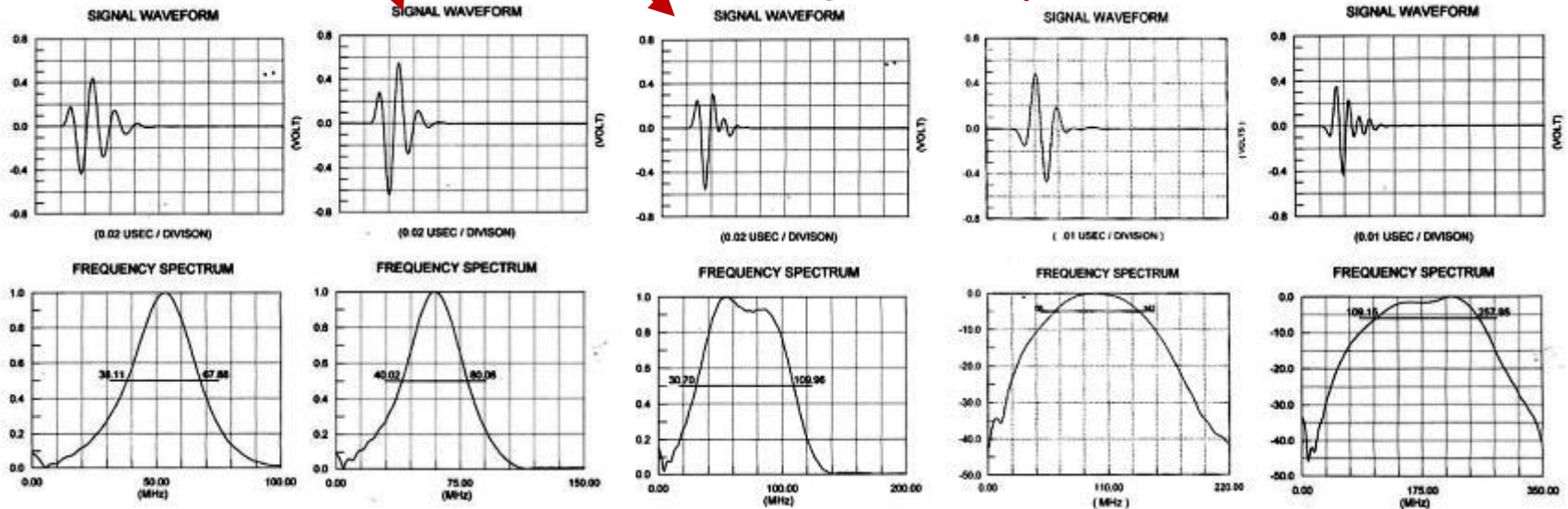
Acquisition of a-c scan data from the multilayered structure using ultrasound frequencies of the order of $>50\text{MHz}$, Resolution of the order of micrometers.

1st layer : $48.5\mu\text{m}$ with sampling $47\mu\text{m}$
2nd layer : $43\mu\text{m}$ with sampling $46\mu\text{m}$



Device - Technique Inventory - Toolbox

Broadband sensors



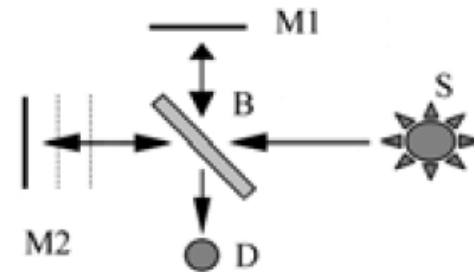
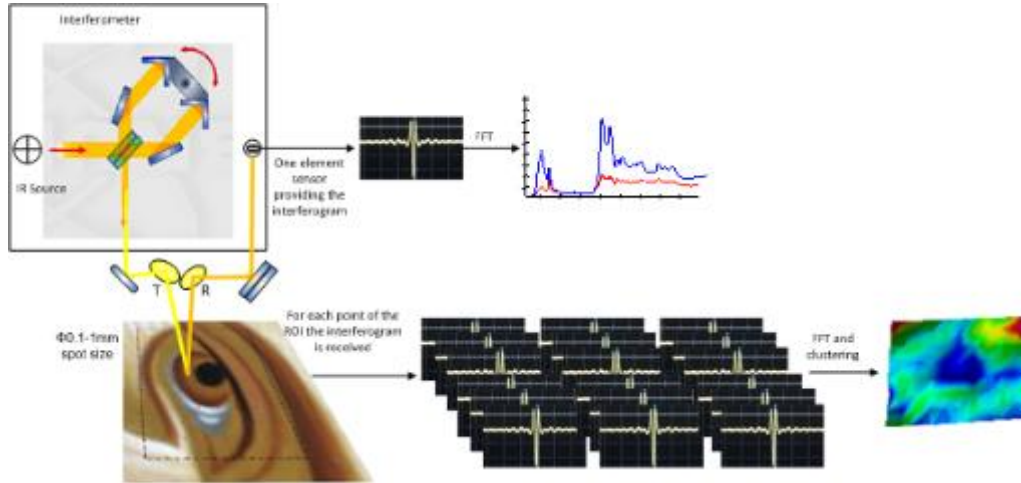
Operating Frequency Range : 38 - 250MHz

Resulting to a resolution from 42 - 3 μ m for an acoustic velocity of 1600m/sec



Device - Technique Inventory - Toolbox

Fourier Transform Infrared Spectroscopy – Mapping Tomography

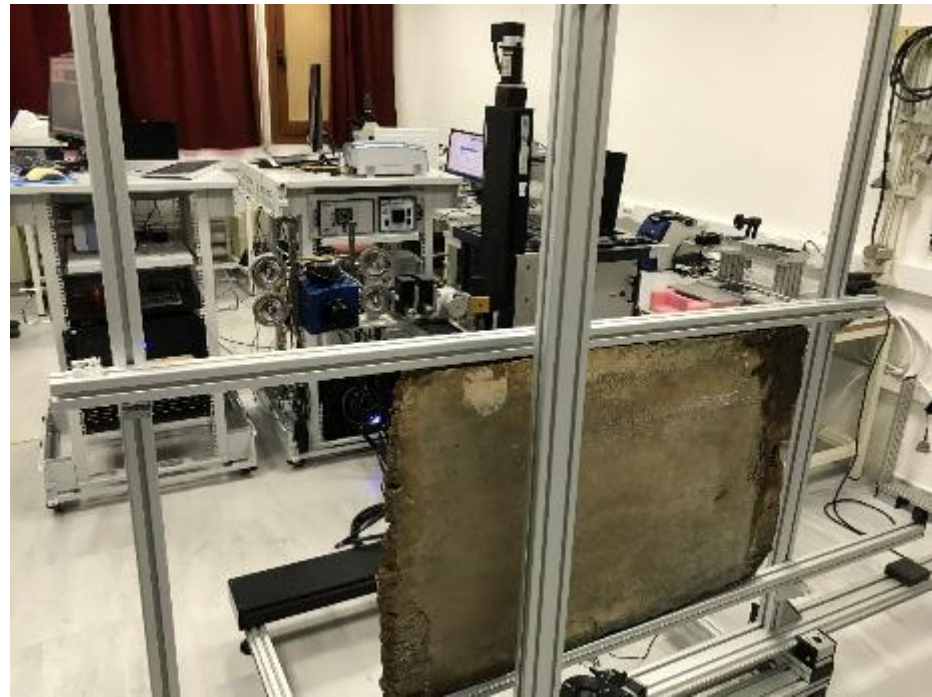
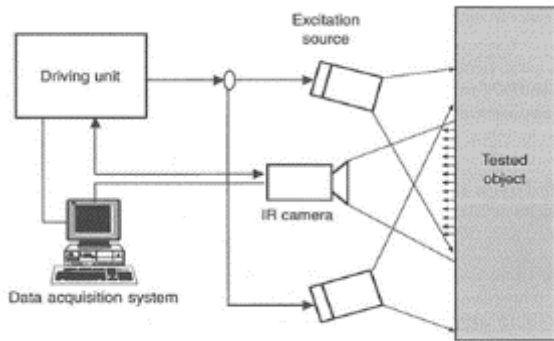


- S: Source
- B: BeamSplitter
- M1: Fixed Mirror
- M2: Moving Mirror
- D: Detector

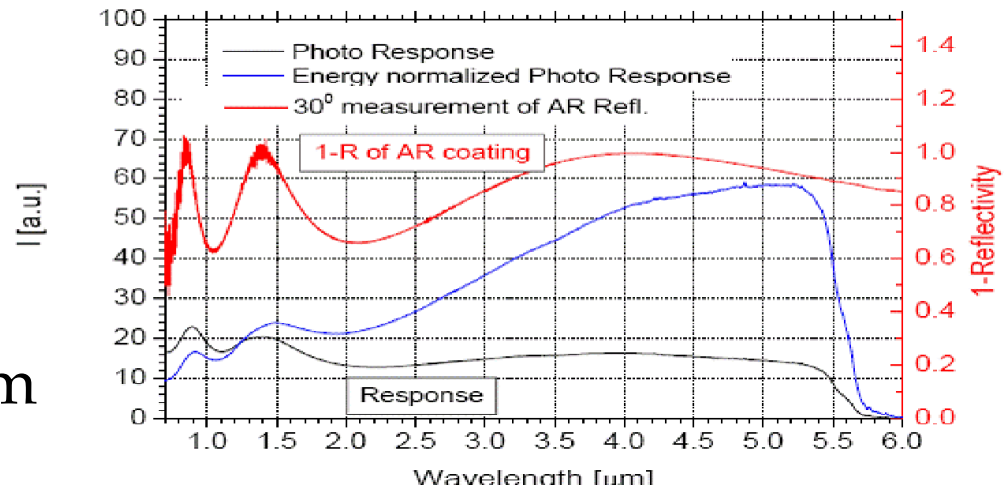


Device - Technique Inventory - Toolbox

IR Camera 1-5 μ m

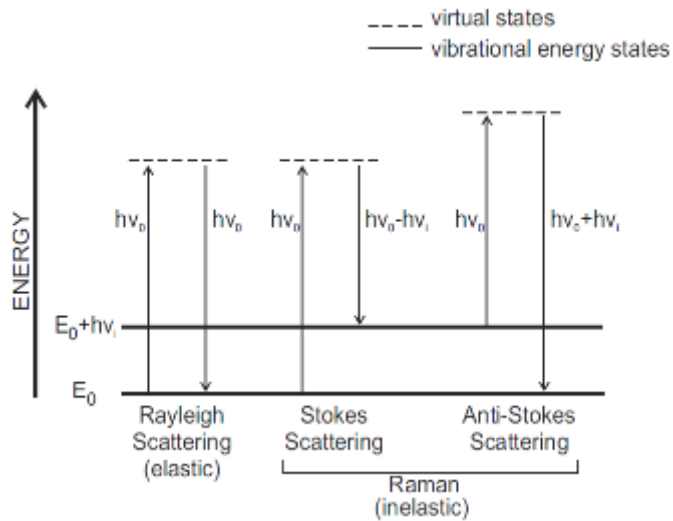


Focal Plane Array InSb 1-5 μ m

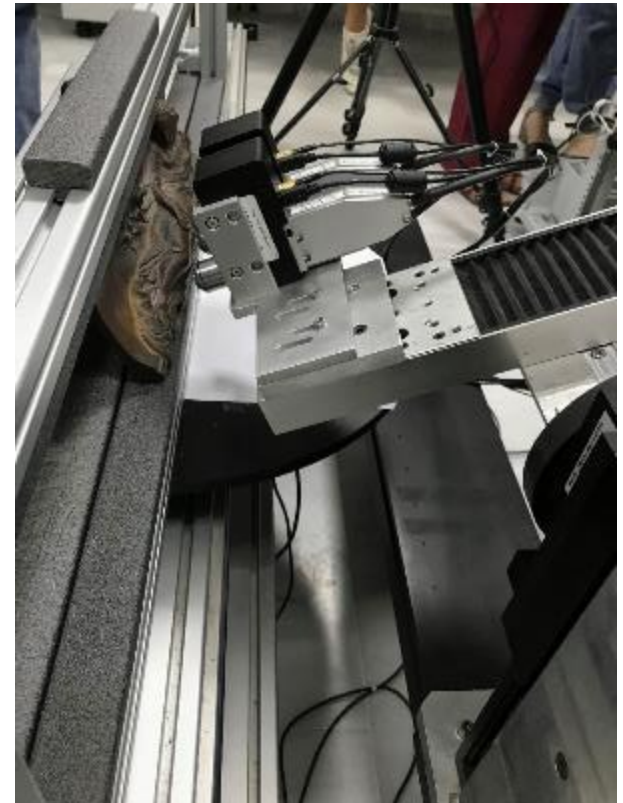


Device - Technique Inventory - Toolbox

Dual wavelength Raman Spectrometer - Mapping spectrophotometer



- Fiber coupled, fiber lengths TBD
- Integrated video camera to ensure correct positioning
- Black Foam or soft Tissue to protect against ambient light and to protect the samples against mechanical damaging

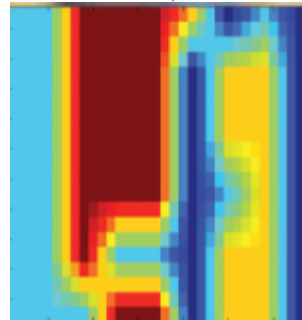
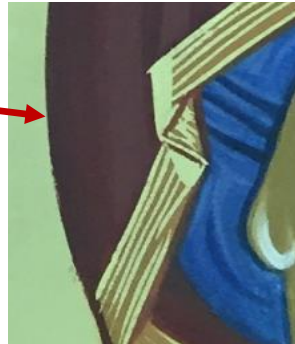




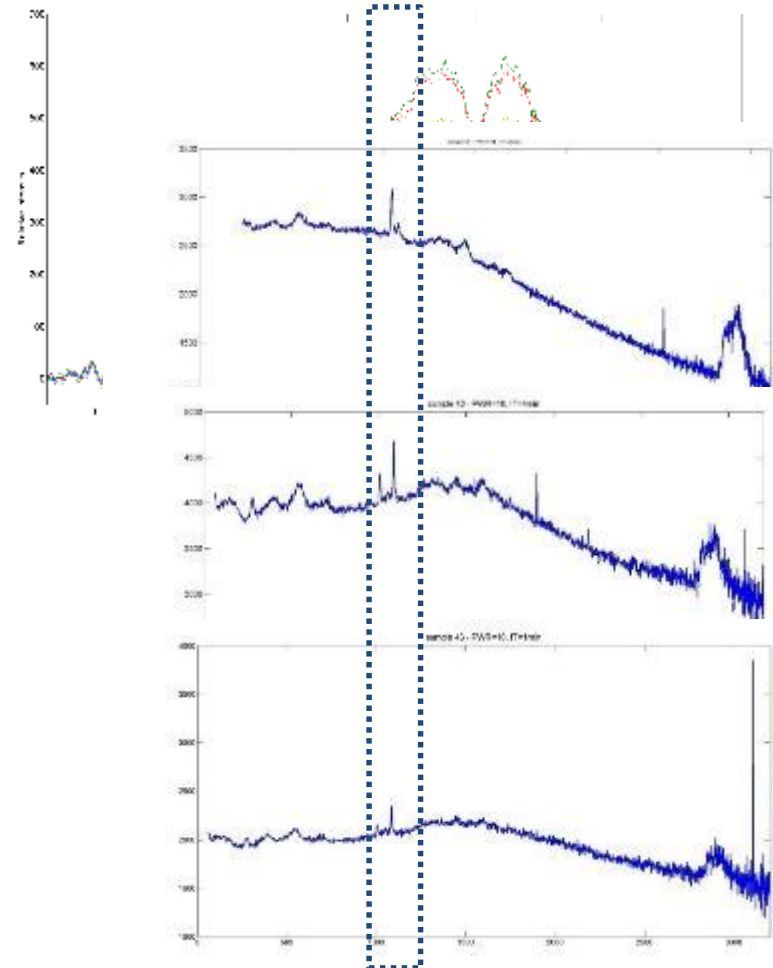
Device - Technique Inventory - Toolbox

Dual wavelength Raman Spectrometer - Mapping spectrophotometer

785 nm & 1064nm laser source

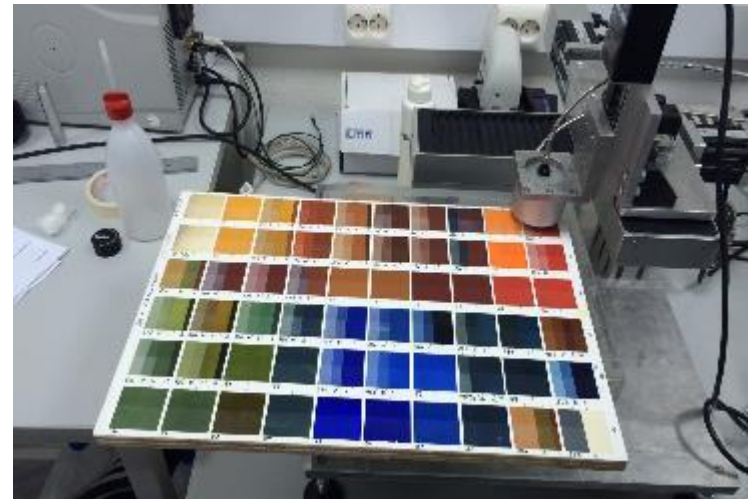
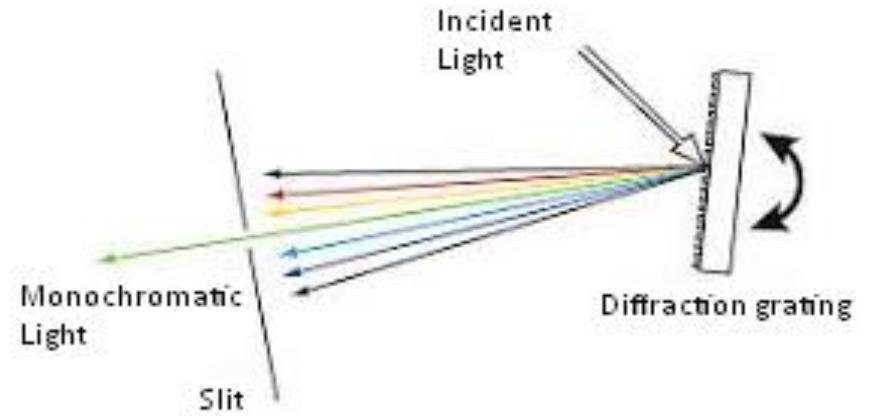
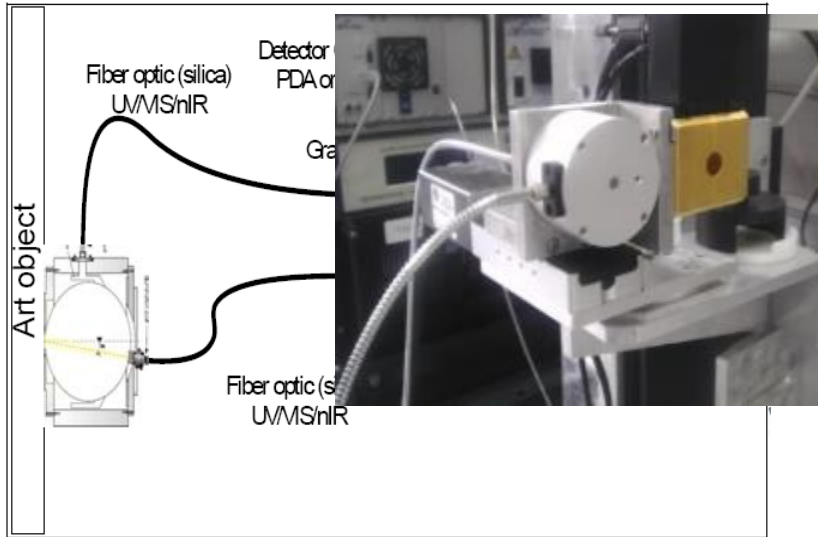


Semantic feature extraction & reconstruction



Device - Technique Inventory - Toolbox

Ultraviolet/Visual (UV/VIS) Scanning

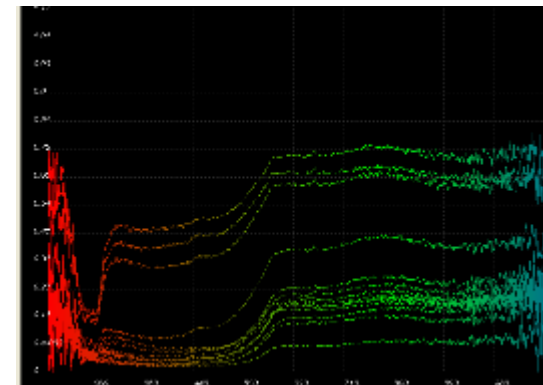
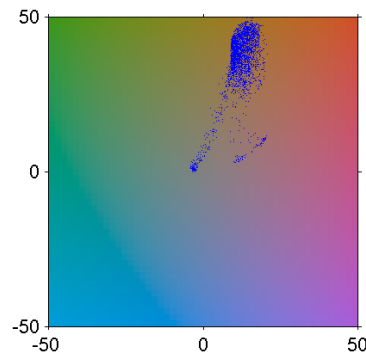
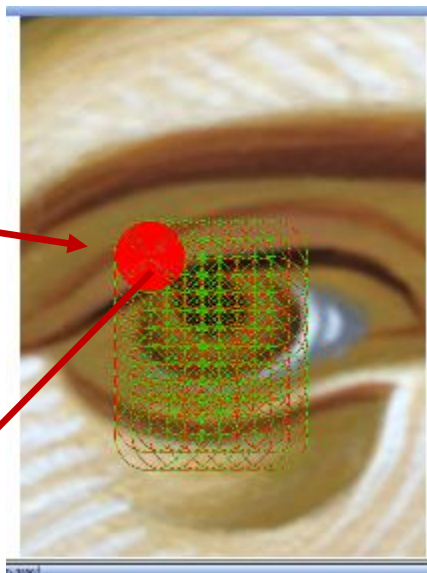




Device - Technique Inventory - Toolbox

Ultraviolet/Visual (UV/VIS) Scanning

$$\begin{bmatrix} R \\ G \\ B \end{bmatrix} = \begin{bmatrix} S_{11} & S_{12} & S_{13} \\ S_{21} & S_{22} & S_{23} \\ S_{31} & S_{32} & S_{33} \end{bmatrix} \cdot \begin{bmatrix} X \\ Y \\ Z \end{bmatrix}$$



$$X = \frac{K}{N} \int_{\lambda} S(\lambda) I(\lambda) \bar{x}(\lambda) d\lambda,$$

$$Y = \frac{K}{N} \int_{\lambda} S(\lambda) I(\lambda) \bar{y}(\lambda) d\lambda,$$

$$Z = \frac{K}{N} \int_{\lambda} S(\lambda) I(\lambda) \bar{z}(\lambda) d\lambda,$$

where

$$N = \int_{\lambda} I(\lambda) \bar{y}(\lambda) d\lambda,$$

$$L^* = 116 f\left(\frac{Y}{Y_n}\right) - 16$$

$$a^* = 500 \left(f\left(\frac{X}{X_n}\right) - f\left(\frac{Y}{Y_n}\right) \right)$$

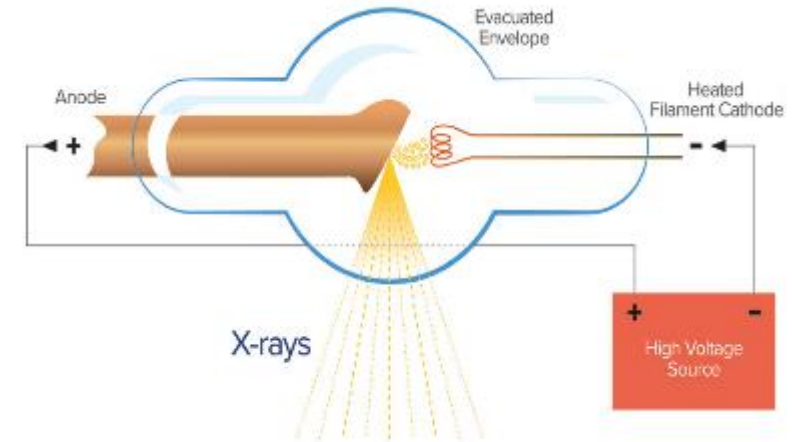
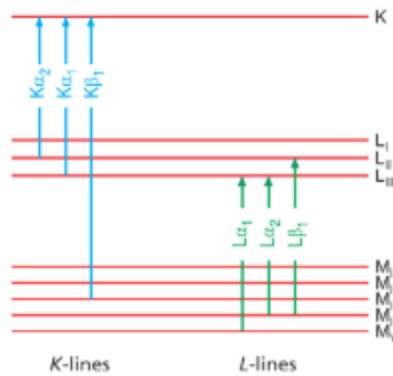
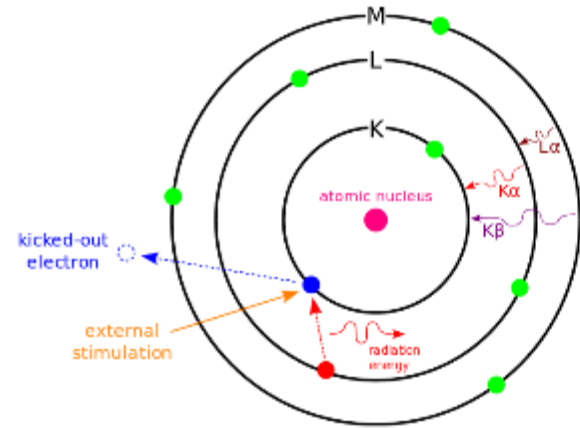
$$b^* = 200 \left(f\left(\frac{Y}{Y_n}\right) - f\left(\frac{Z}{Z_n}\right) \right)$$

where

$$f(t) = \begin{cases} \sqrt[3]{t} & \text{if } t > \delta^3 \\ \frac{t}{3\delta^2} + \frac{4}{29} & \text{otherwise} \end{cases}$$

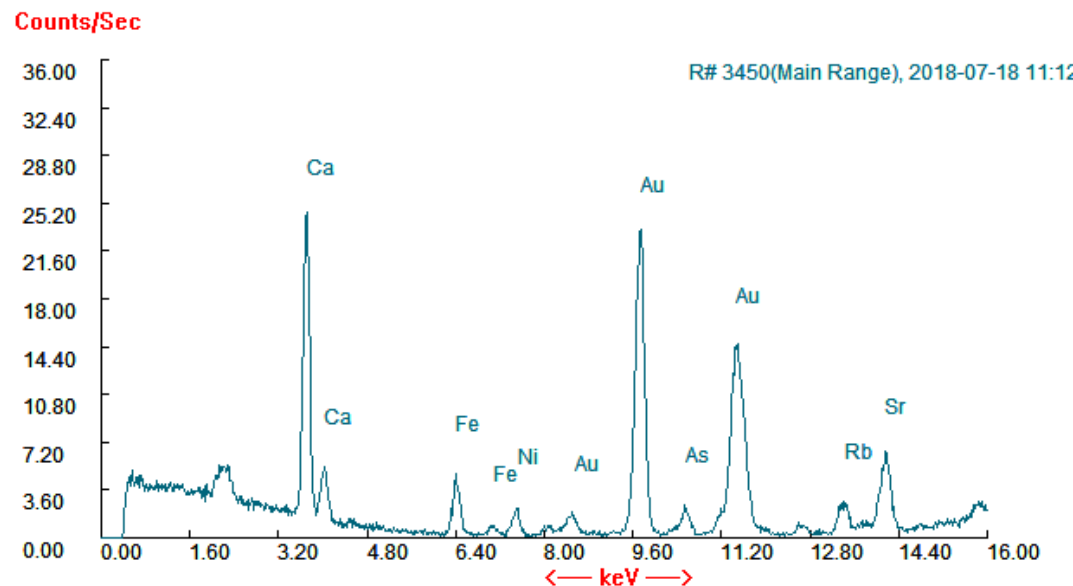
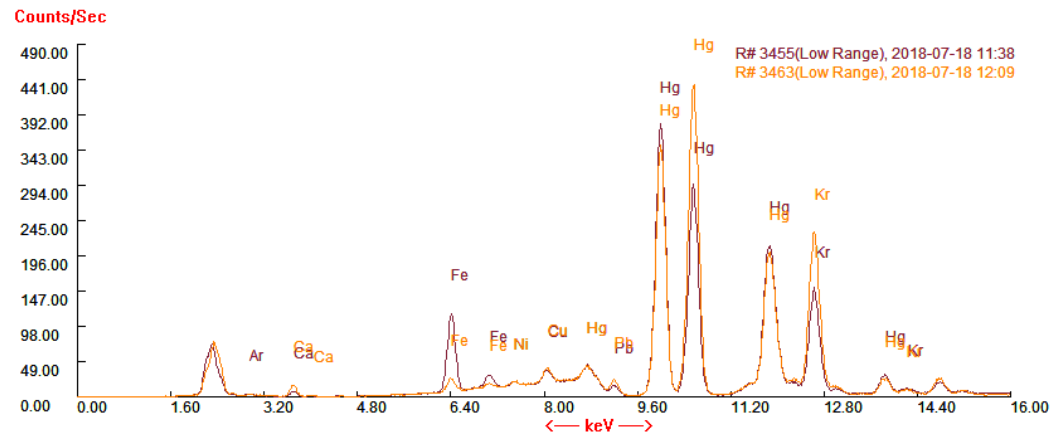
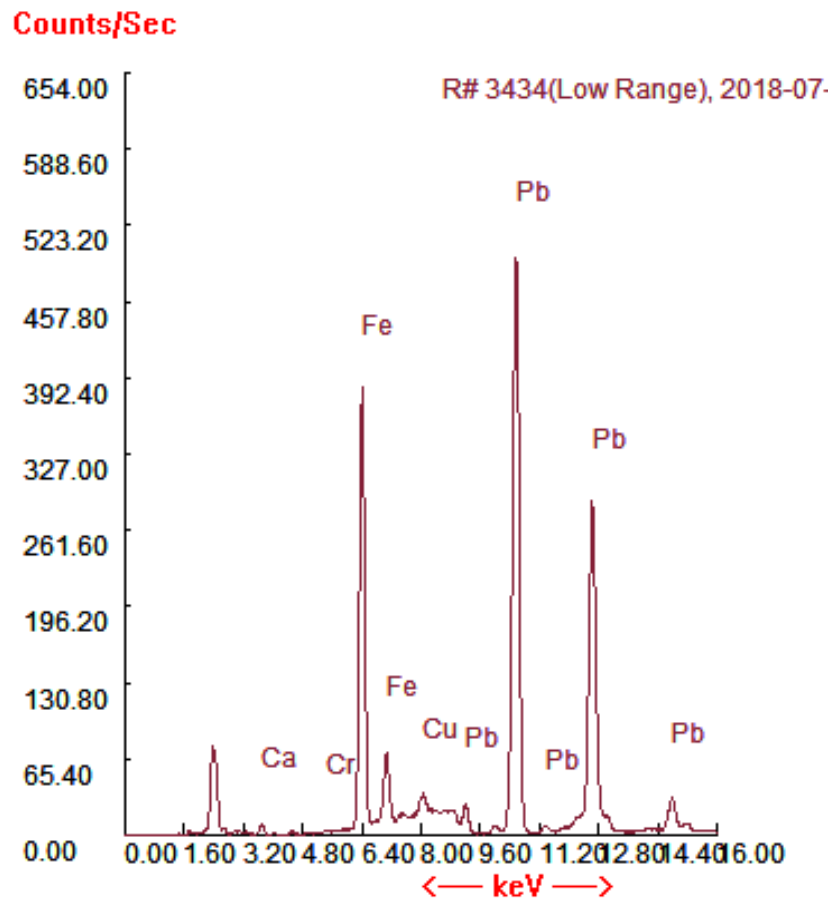
Device - Technique Inventory - Toolbox

X-Ray Fluorescence (XRF)



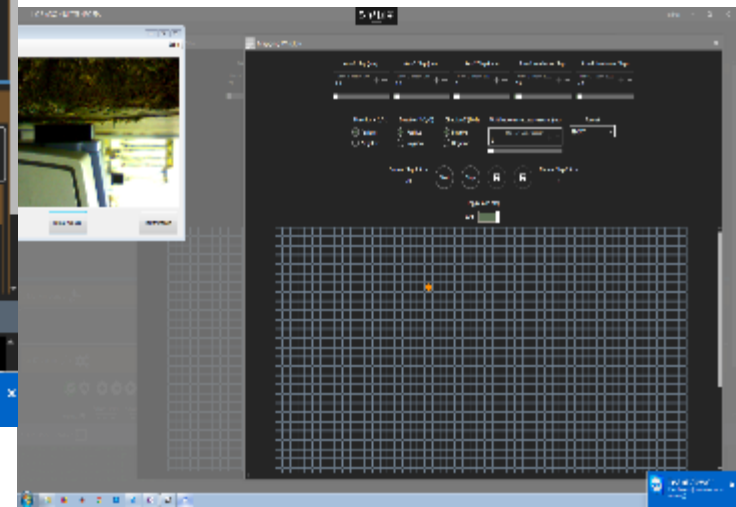
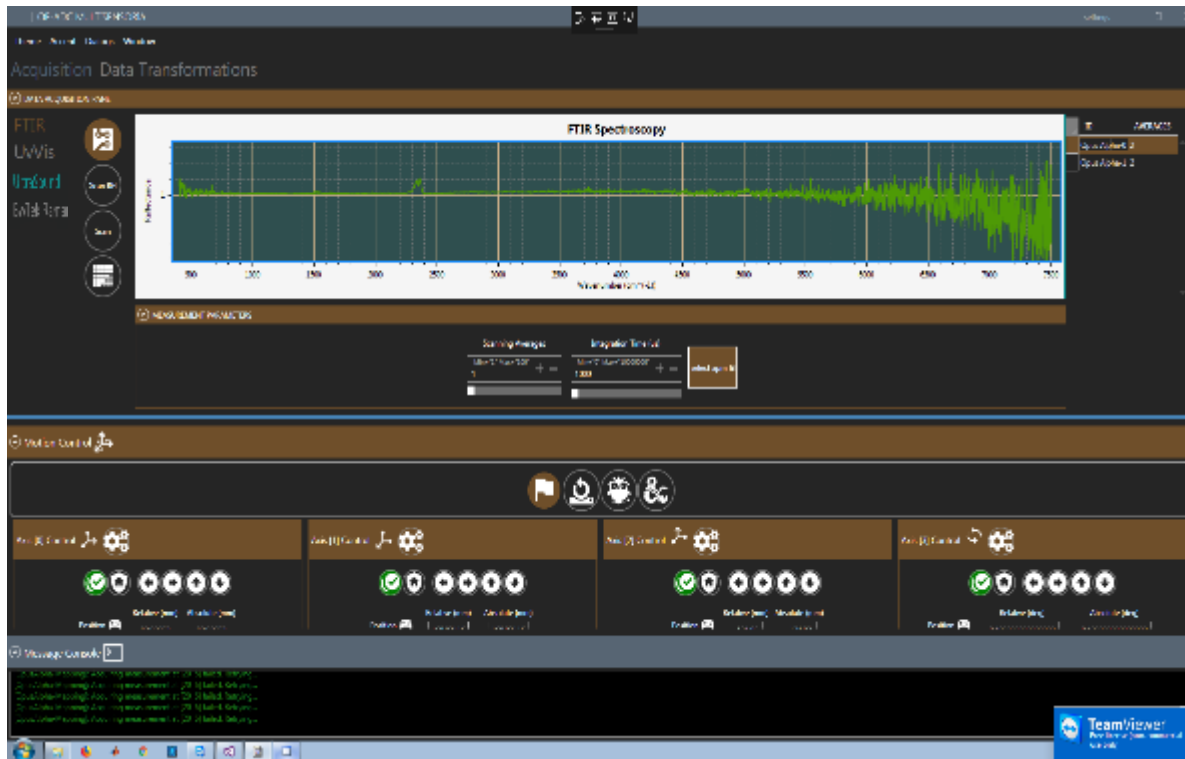


XRF measurements



Device - Technique Inventory - Toolbox

MultiSensorial acquisition and processing Platform



- Pre-calibration of the iTomography devices
- The architecture of the platform follows the Model-View-Viewmodel (MVVM) pattern
- Surface mapping operations
- Fine positioning motion control system supports resolutions down to 1 μm
- DICONDE standard is followed



Cultural Heritage Objects





Cultural Heritage Objects

A ... "trip" back to the past ...
with all the technologies on board

ACTUAL

Database
«Ormylia» Foundation

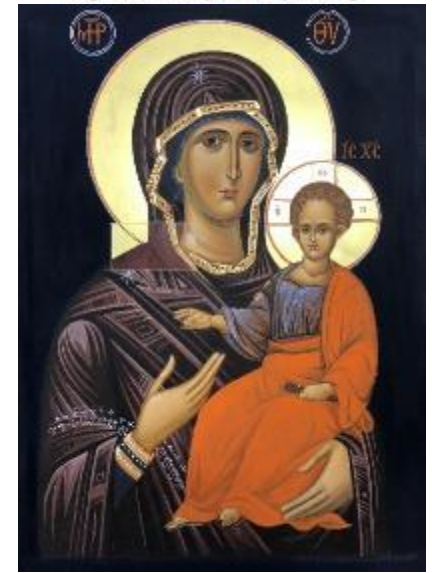


Figure 2: Initial painting



Figure 3: Overpainted painting

CLONE





Cultural Heritage Objects

- Realization of a clone of the icon of Hodegetria
- Accurate historical reconstruction of the 14th century technique



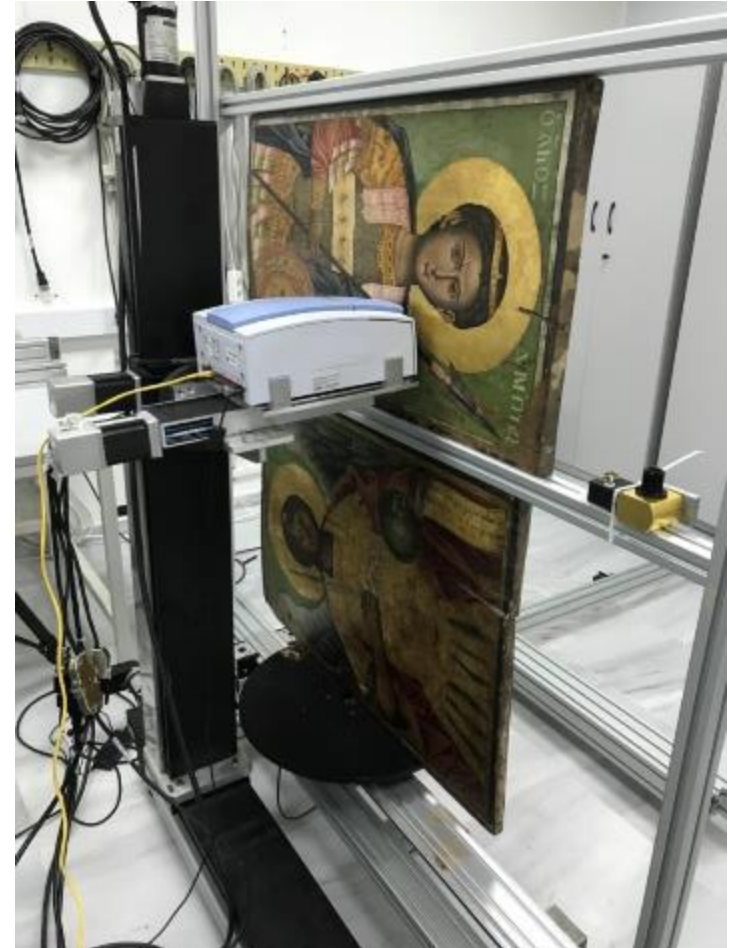


Point – Scanning Region of Interest and Imaging measurements

Physicochemical defects via ageing, creation materials and admixtures identification. Elemental analysis and supporting materials detection

Modalities

- FTIR spectrometer
- Raman spectrometer
- XRF spectrometer



Registration Procedure and Algorithms

Registration

- Area-based
 - Cross-correlation
- Feature-based
 - Homography matrix via iterative algorithms such as RANSAC
 - Feature detection via SIFT, SURF and ORB algorithms



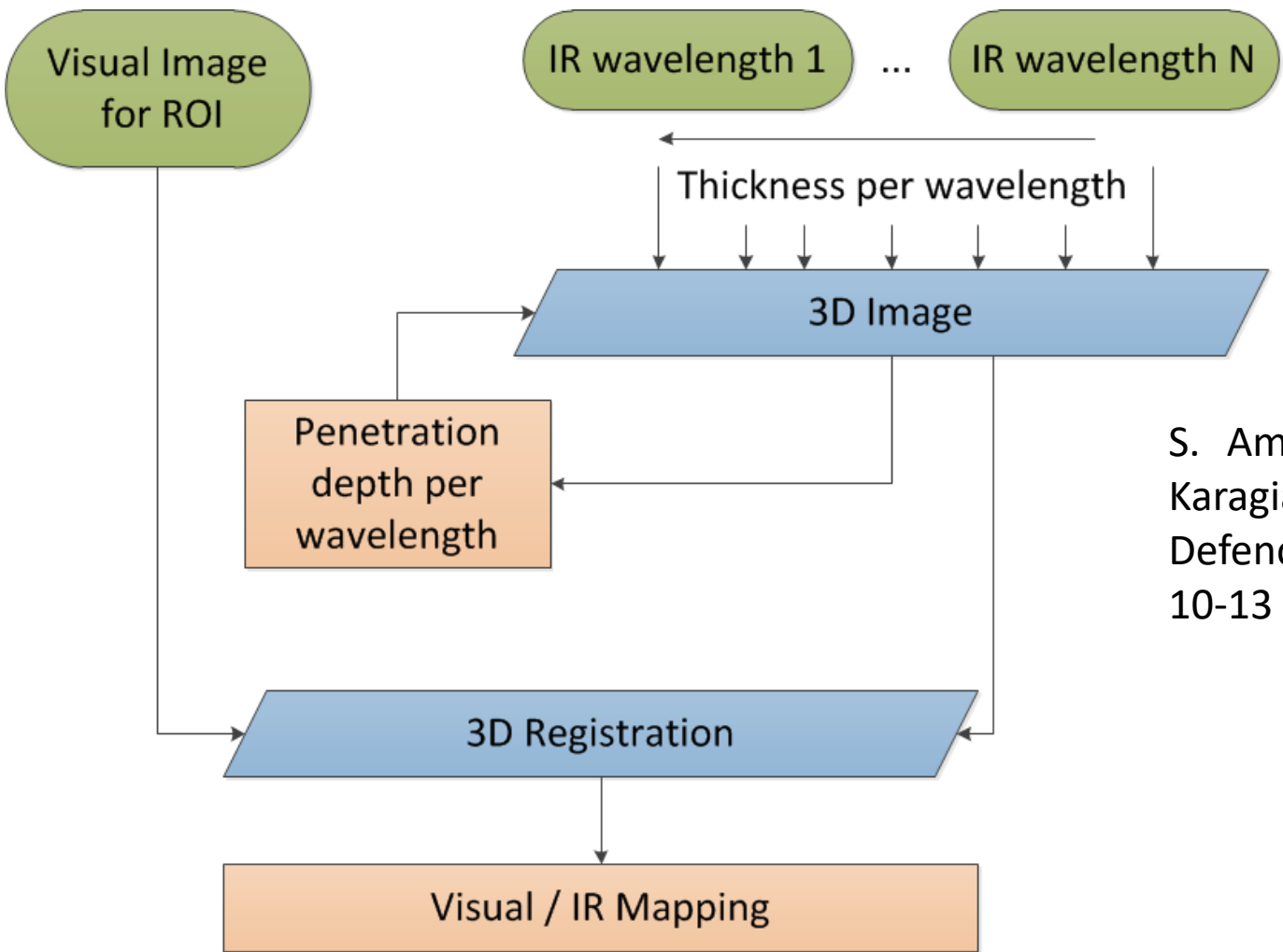
Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... “i” Tomography - iTomography

Infrared mapping spectroscopy,

Infrared hyperspectral mapping imaging 1.3 – 5 - 26 μ m



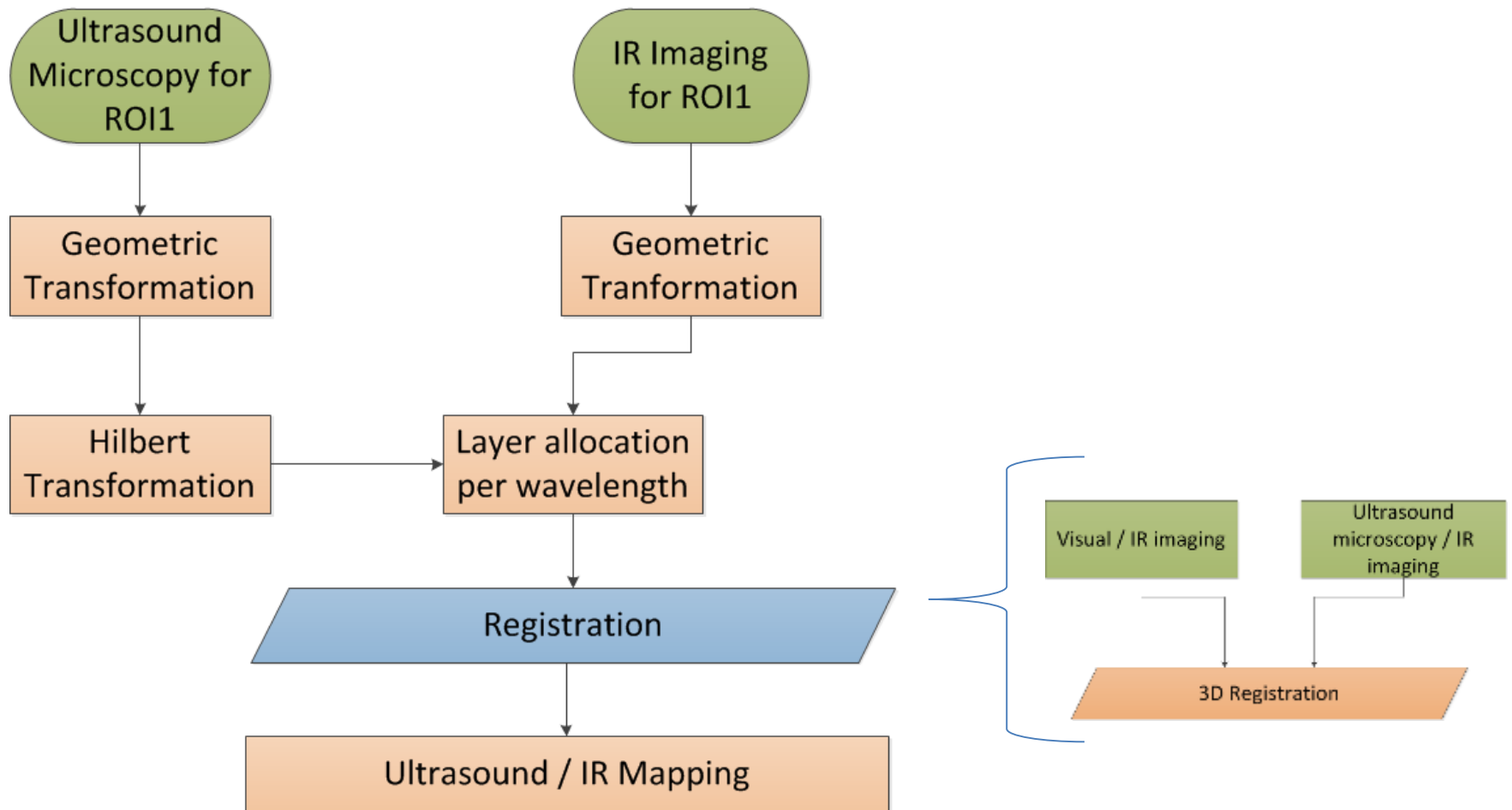
S. Amanatiadis, Apostolidis, G. Karagiannis, SPIE Security plus Defence 2018, Berlin, Germany, 10-13 September 2018

Combination/ Fusion of the data –

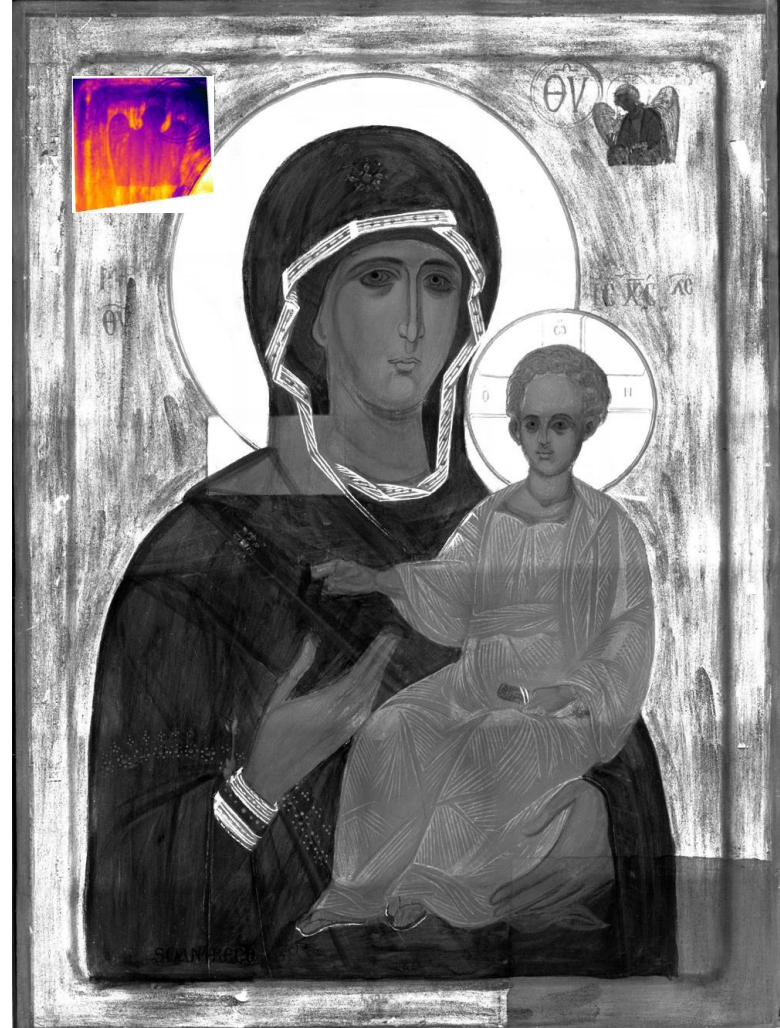
(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... “i” Tomography - iTomography

Fusion



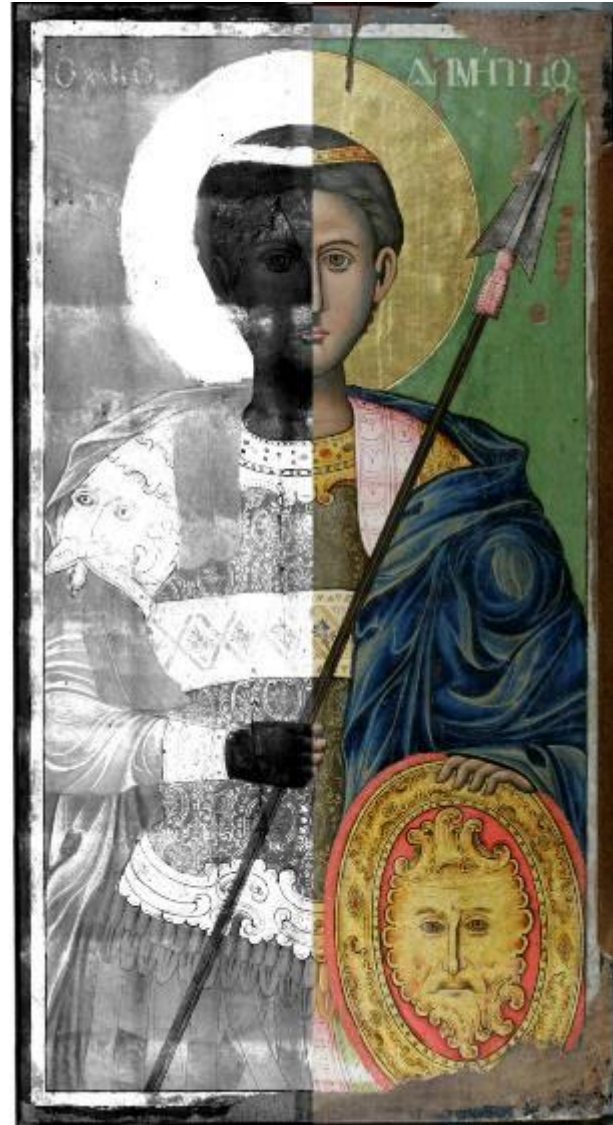
**Combination/ Fusion of the data –
(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)
Tomography ... “i” Tomography - iTomography**





Combination/ Fusion of the data –
(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS,
...) Tomography ... "i" Tomography - iTomography

St. Demetrius

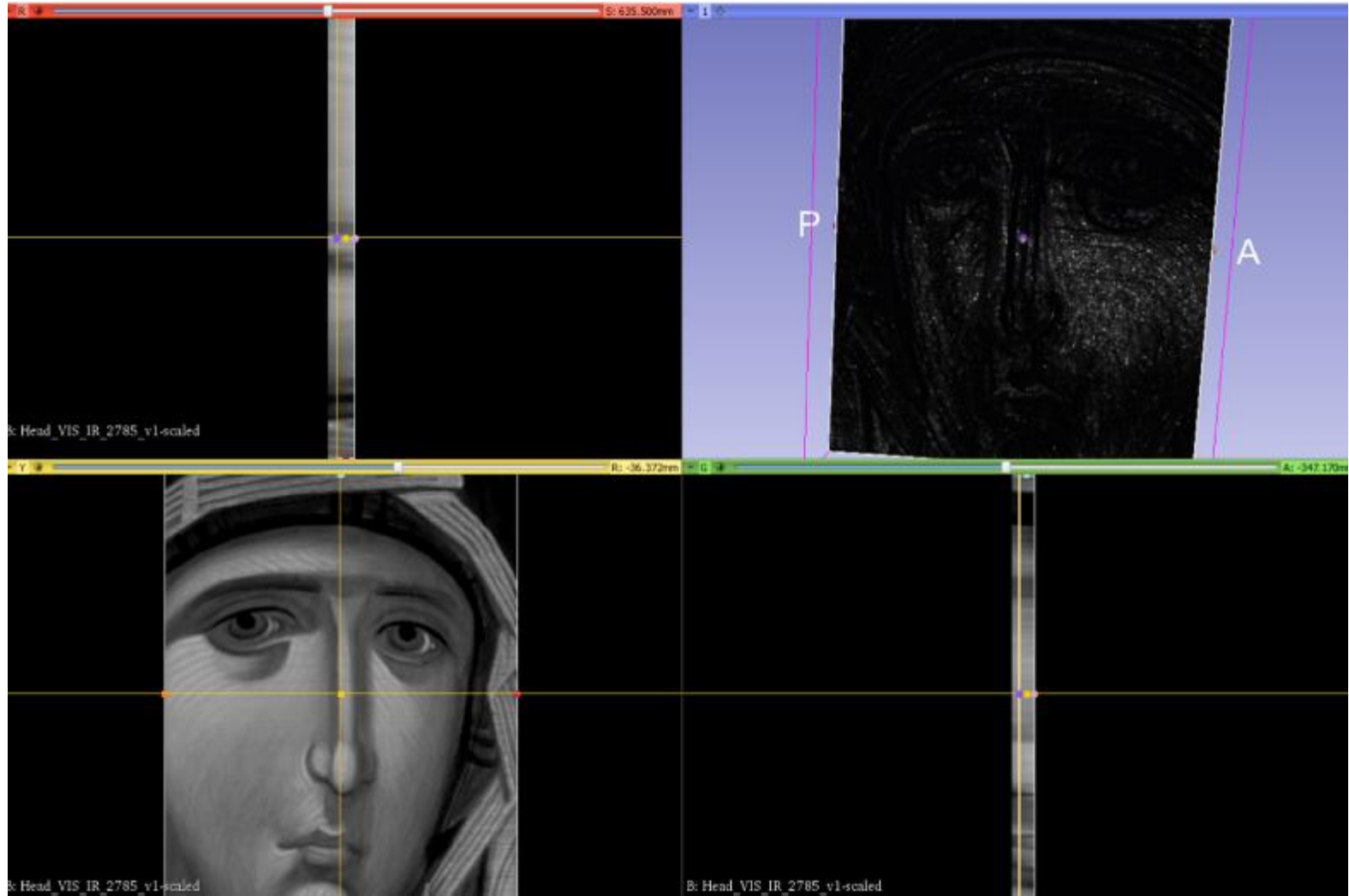


Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

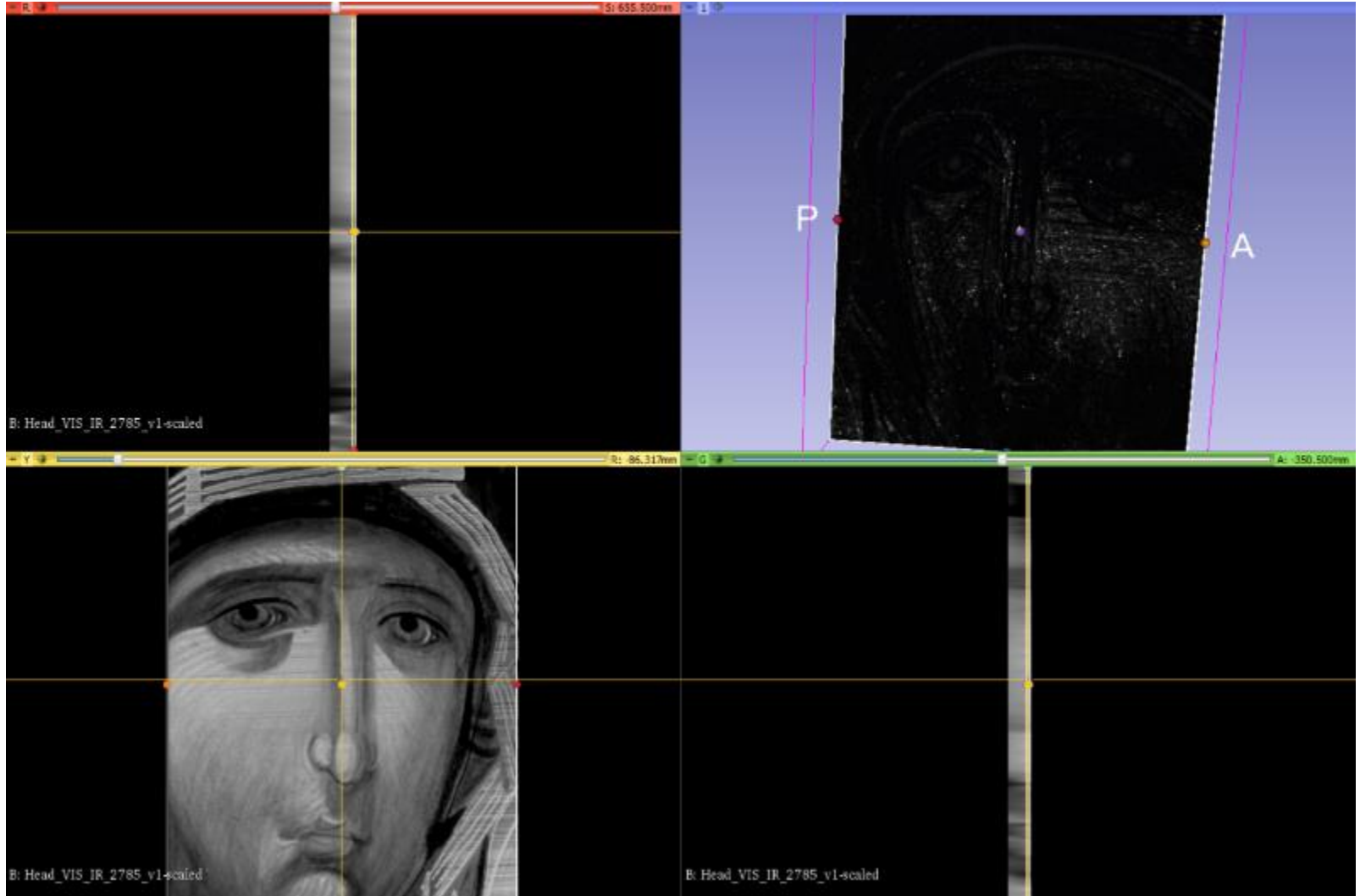
Tomography ... “i” Tomography - iTomography

Infrared mapping spectroscopy
Infrared imaging 1.8-2.8 μ m



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography

Infrared mapping spectroscopy
Infrared imaging 2.8-5 μ m

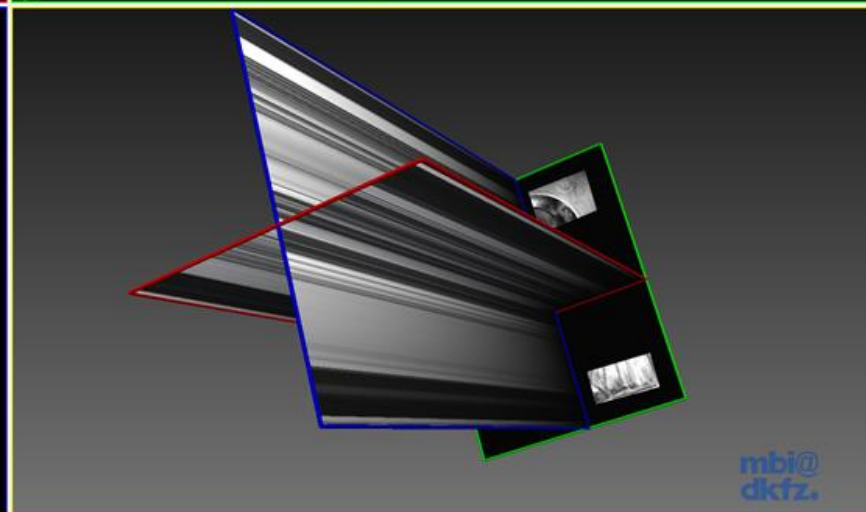
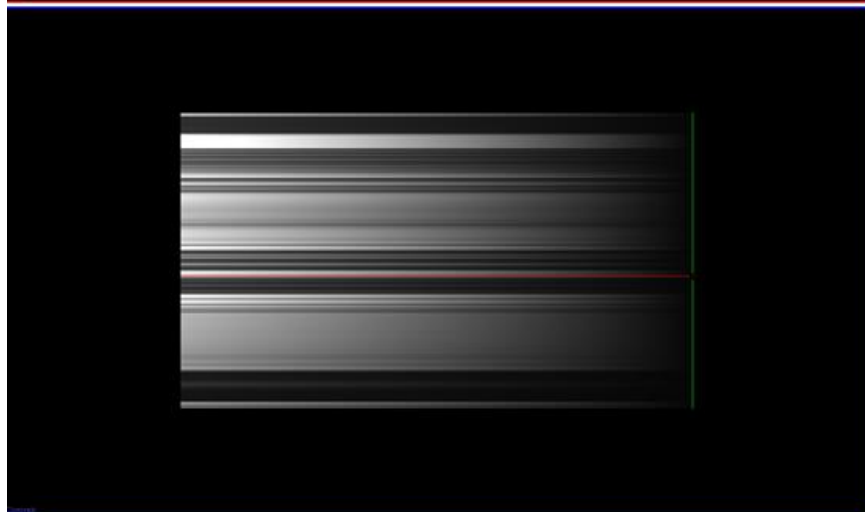
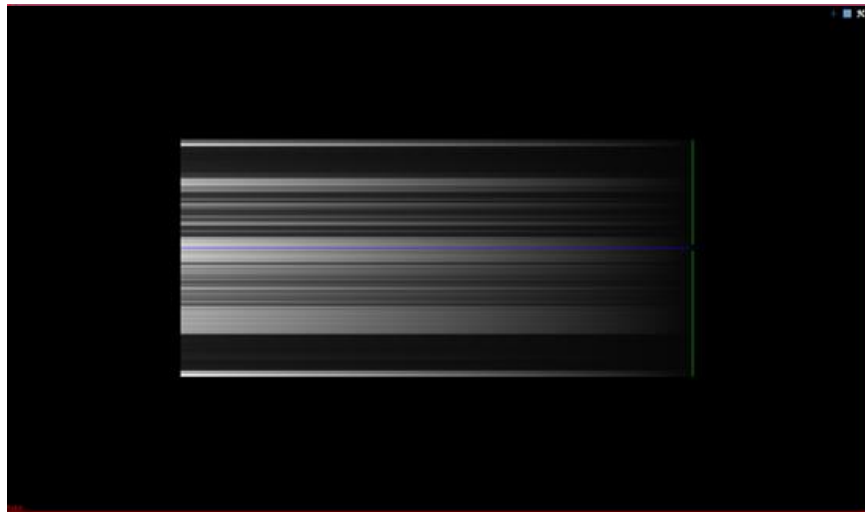


Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... "i" Tomography - iTomography

Infrared mapping spectroscopy
Infrared imaging 1.5-5µm



Combination/ Fusion of the data –
(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)
Tomography ... “i” Tomography - iTomography

Infrared imaging 1.5-5µm
XENICS XMID InSb 1-5µm



Infrared imaging 8-14µm
FLIR i60



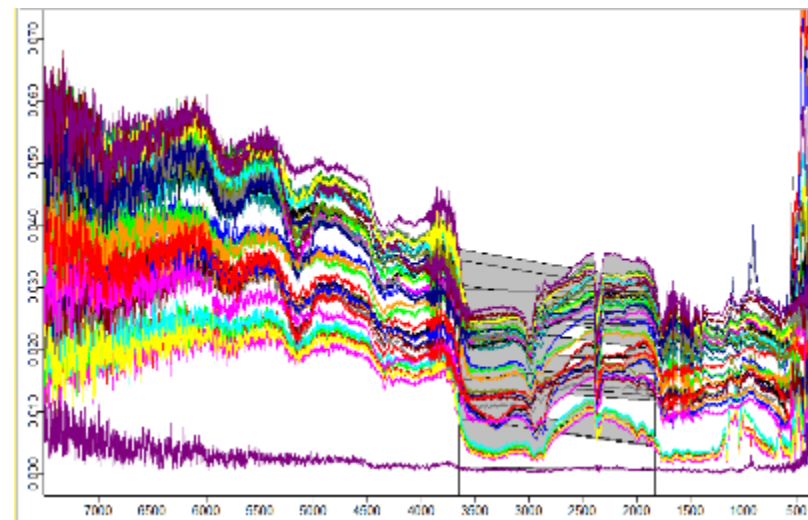
Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... “i” Tomography - iTomography

Infrared mapping spectroscopy,

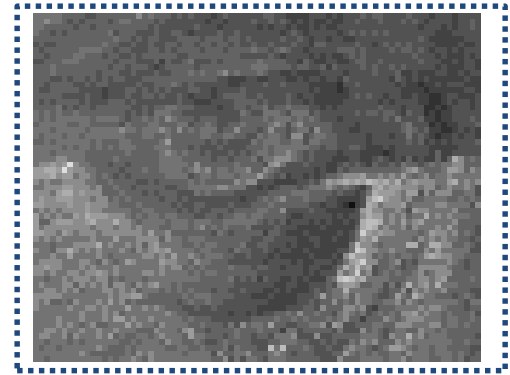
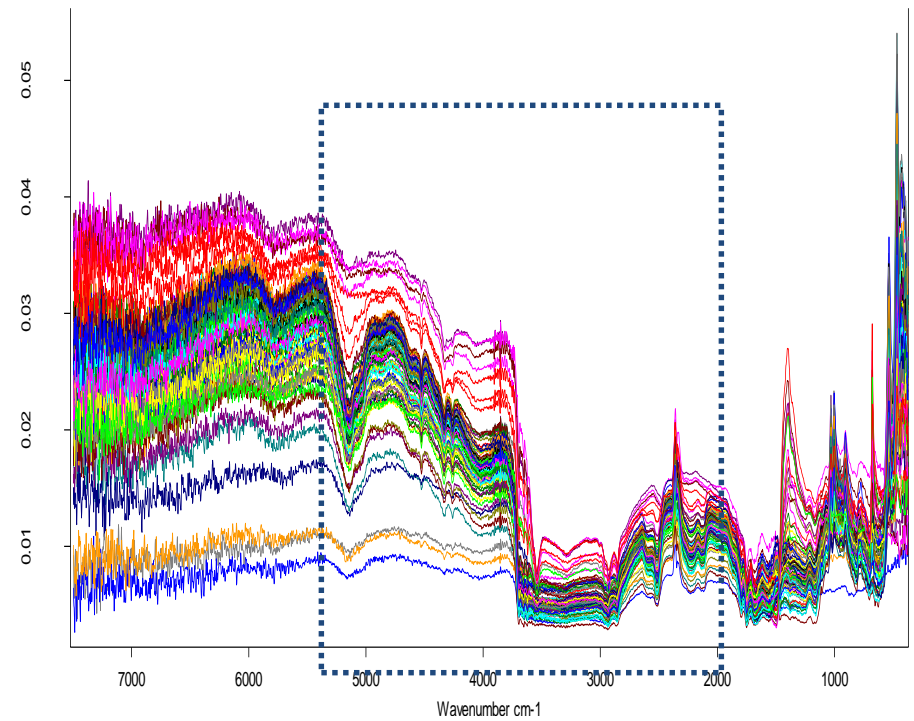
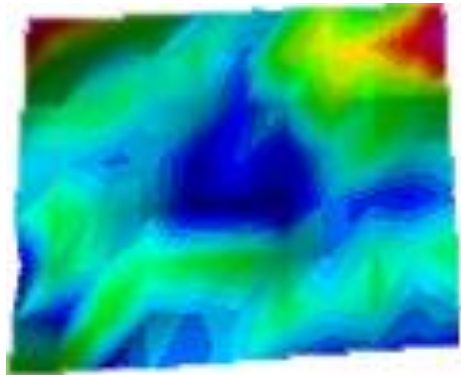
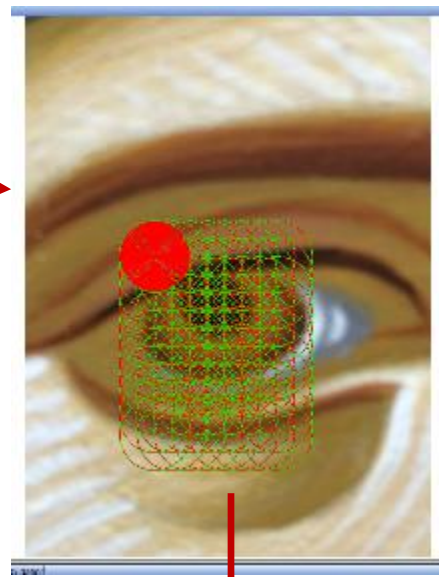
Infrared hyperspectral mapping imaging 1.3 – 5 - 26 μm



Combination/ Fusion of the data –

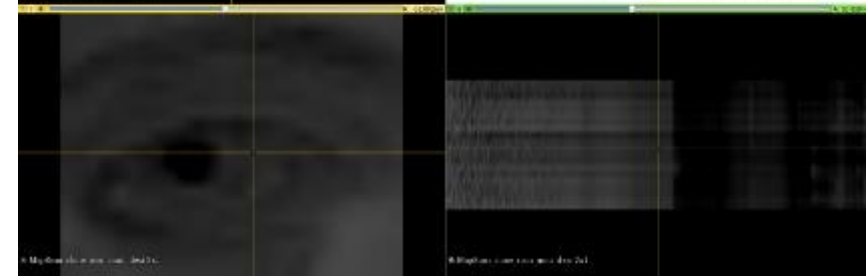
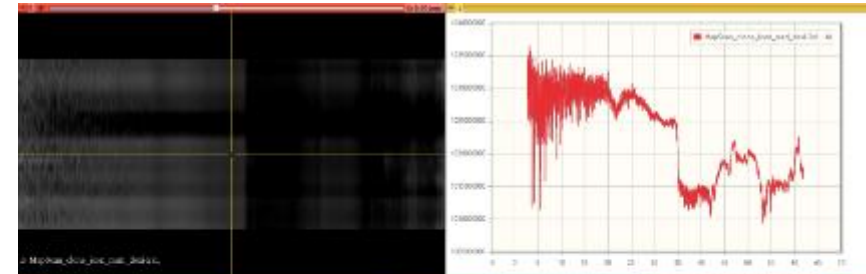
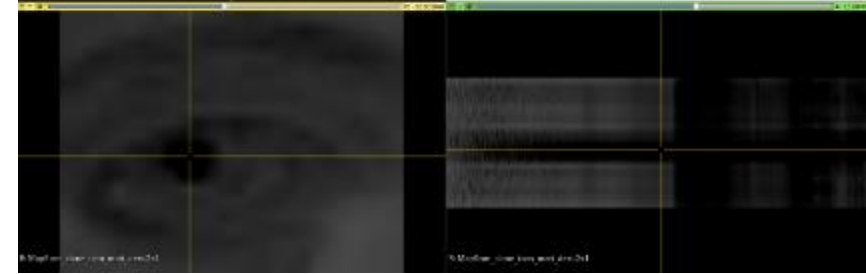
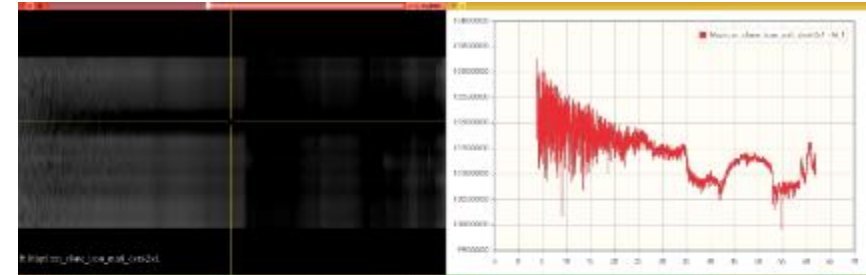
(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... “i” Tomography - iTomography



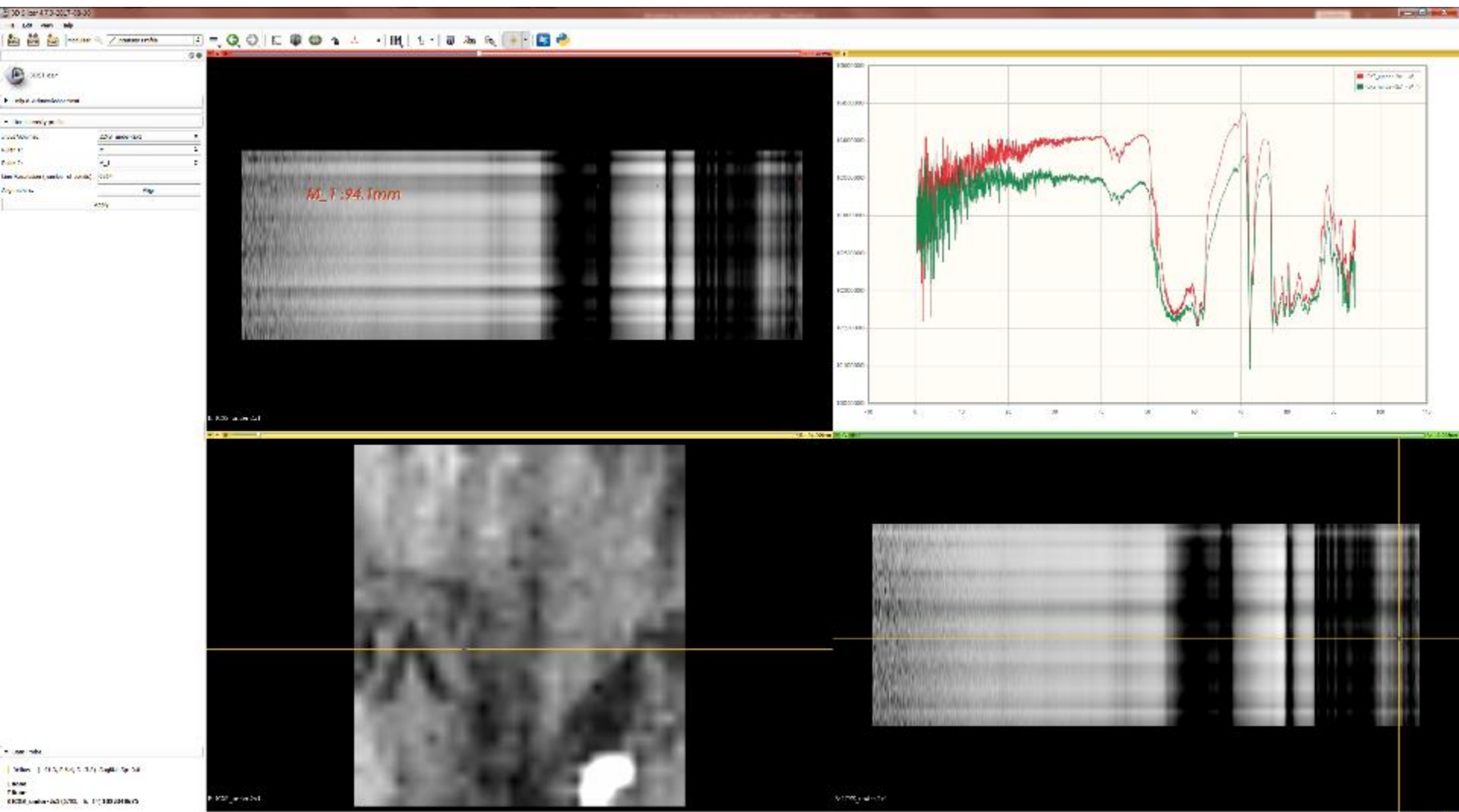


Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



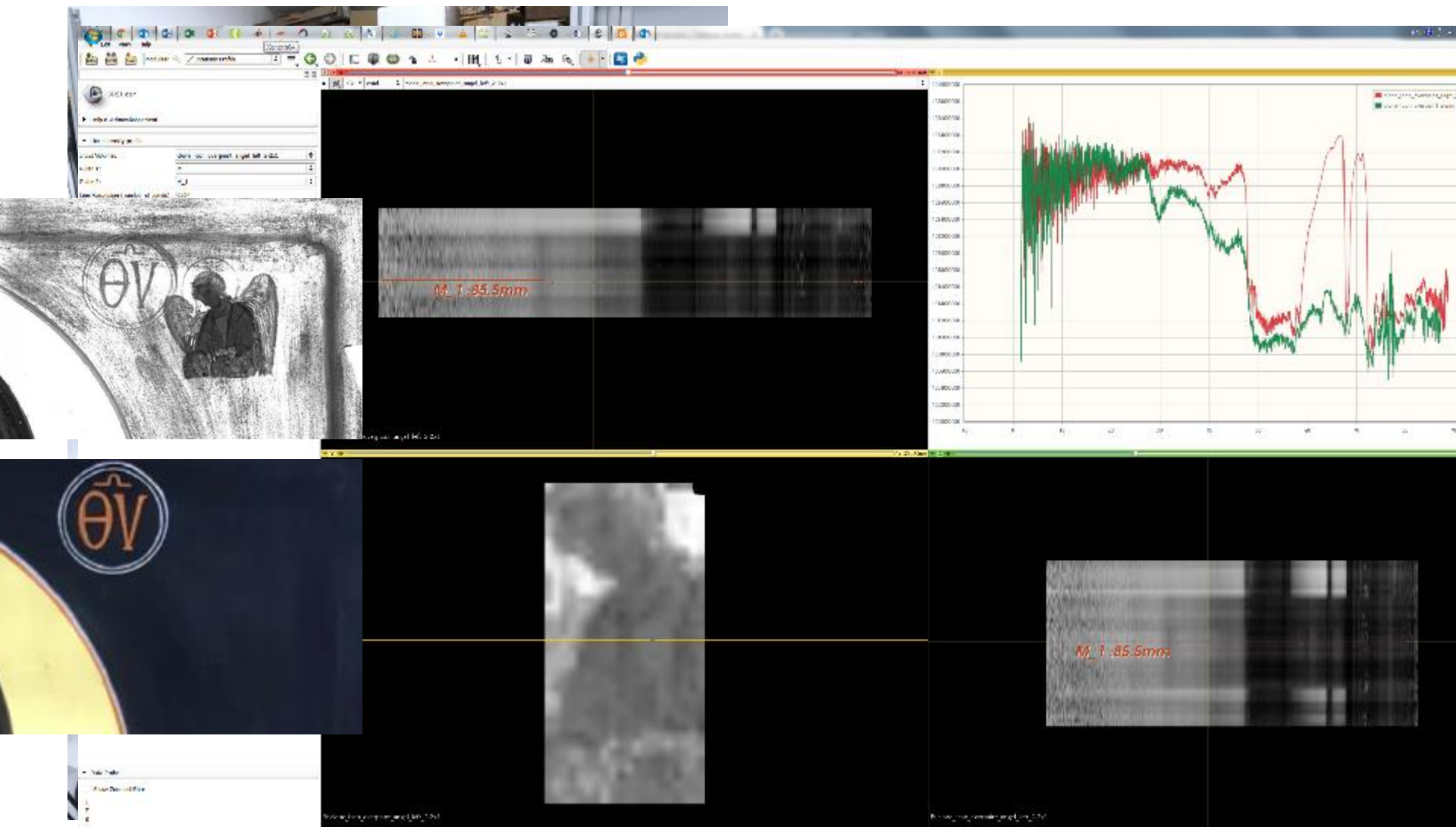


Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



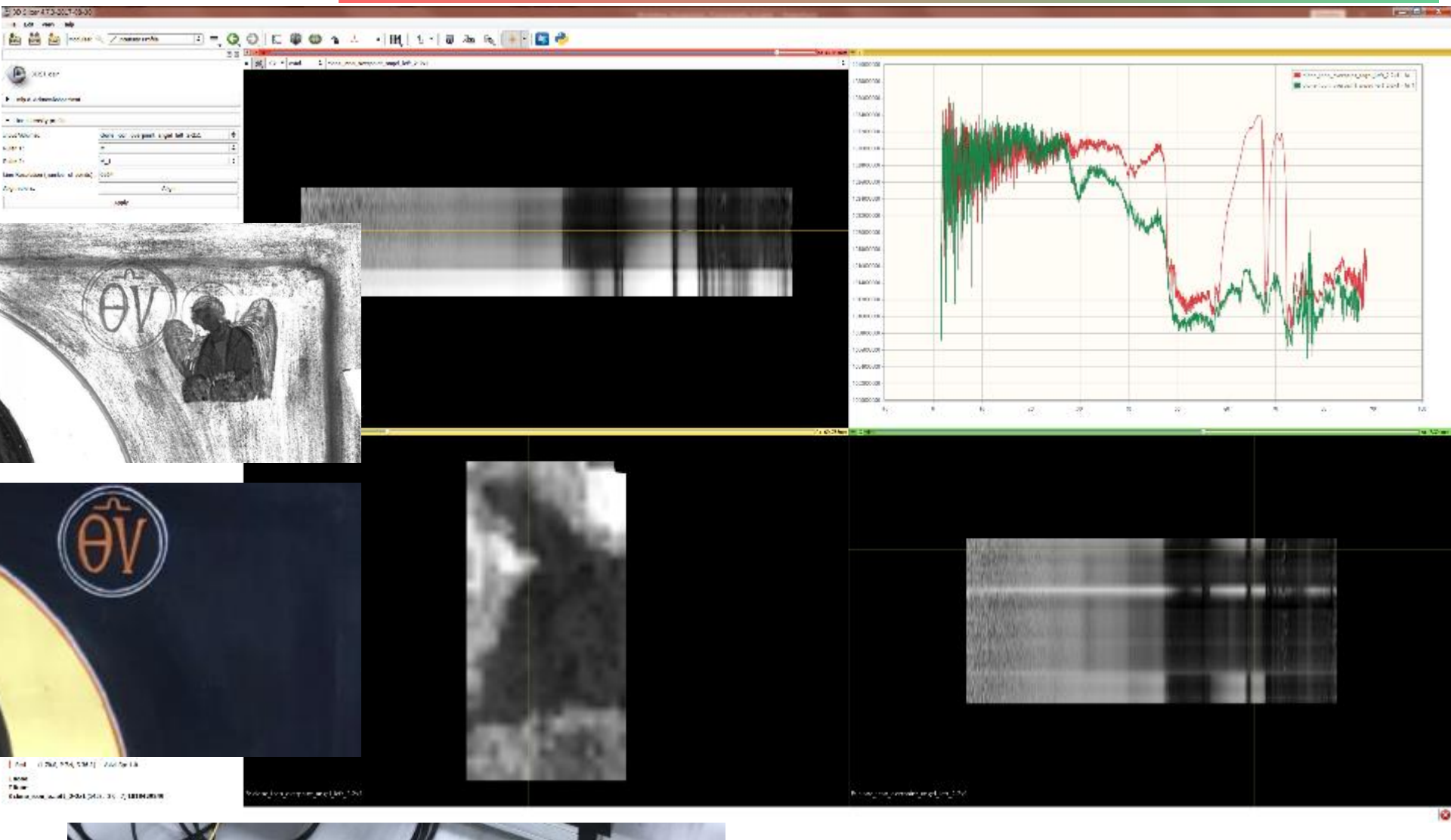


Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



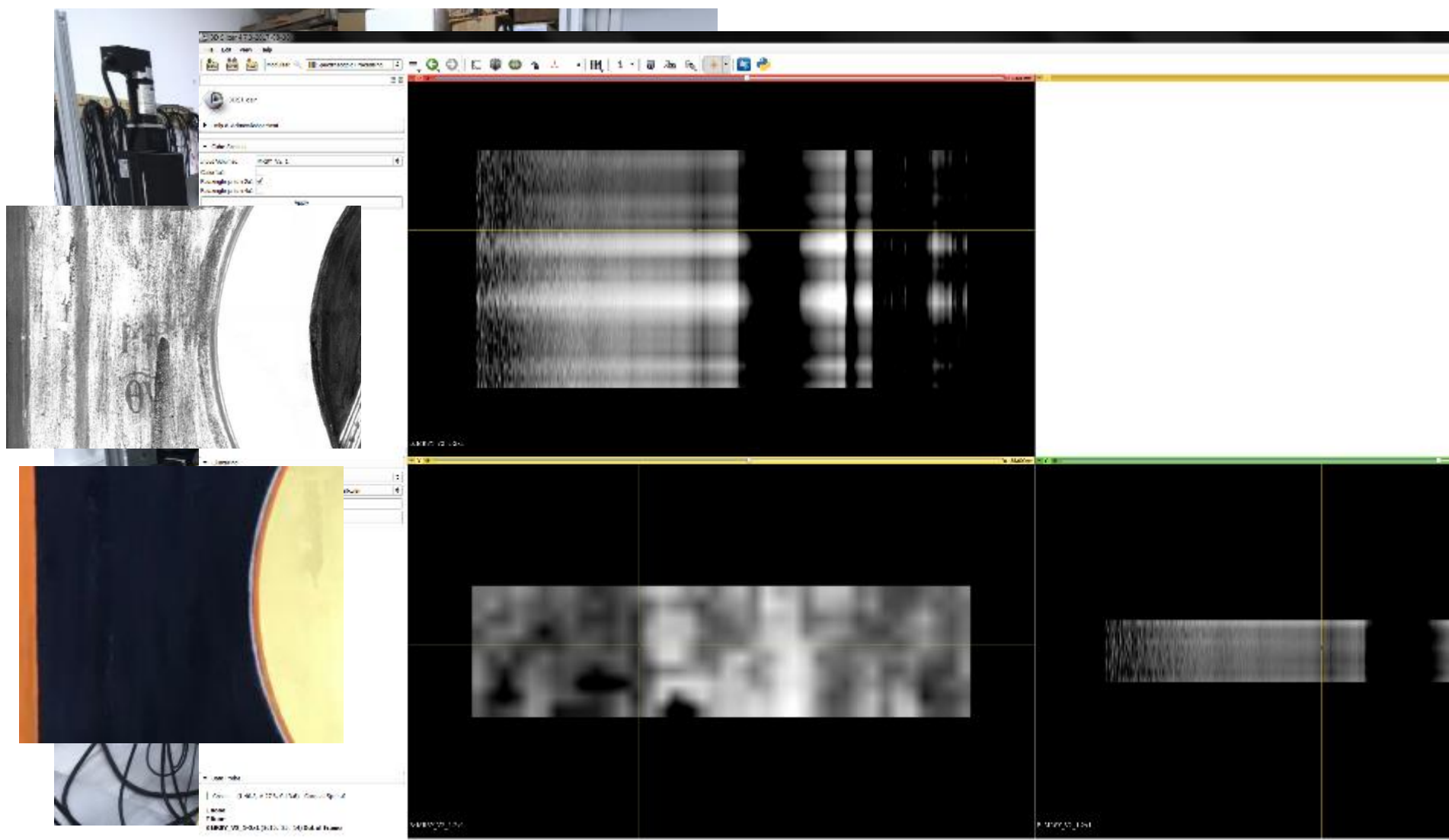


Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



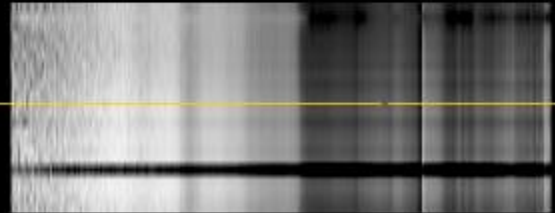
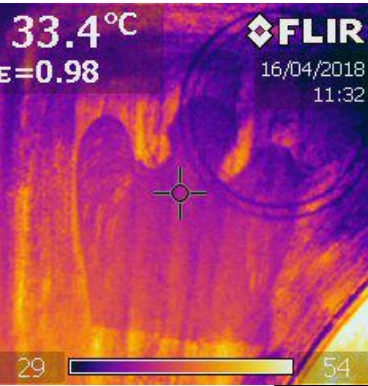


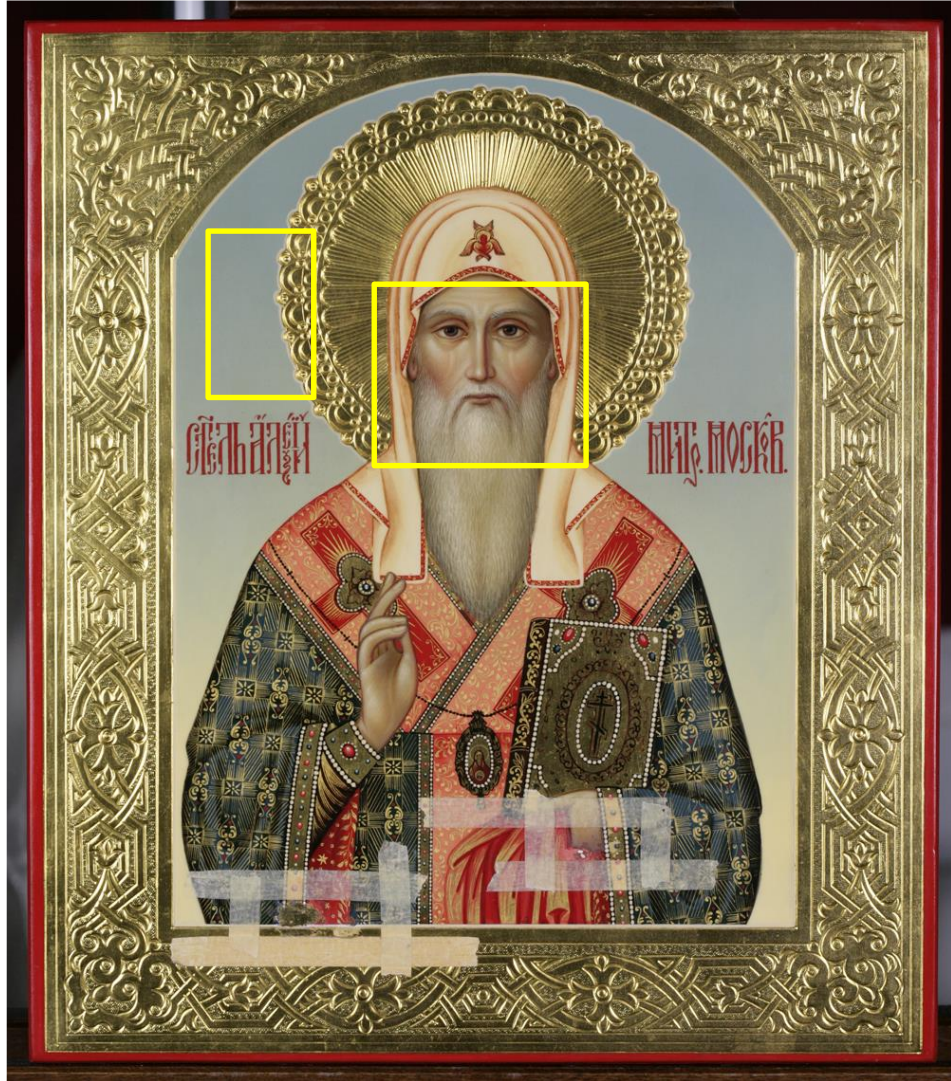
Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography





Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography





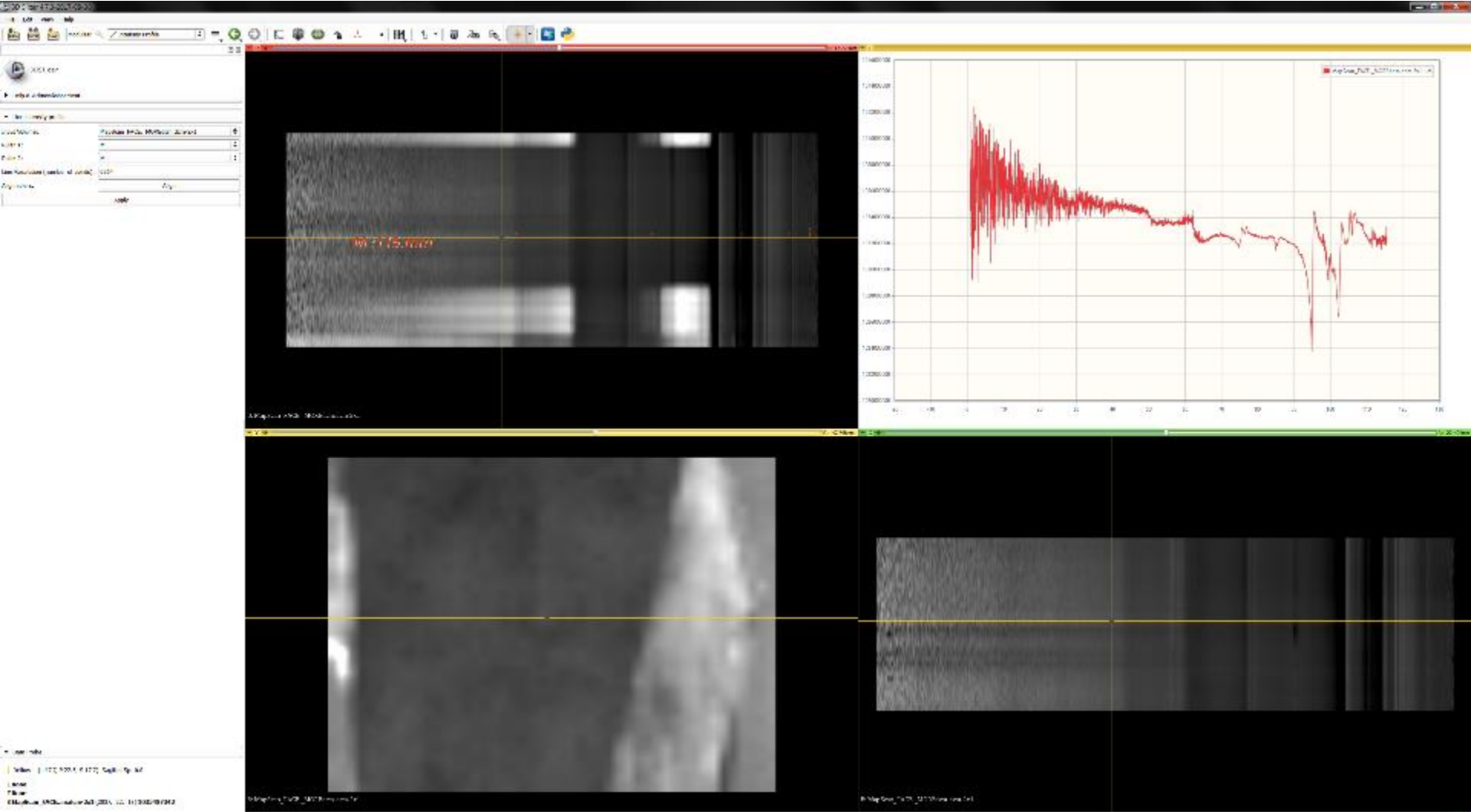
Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

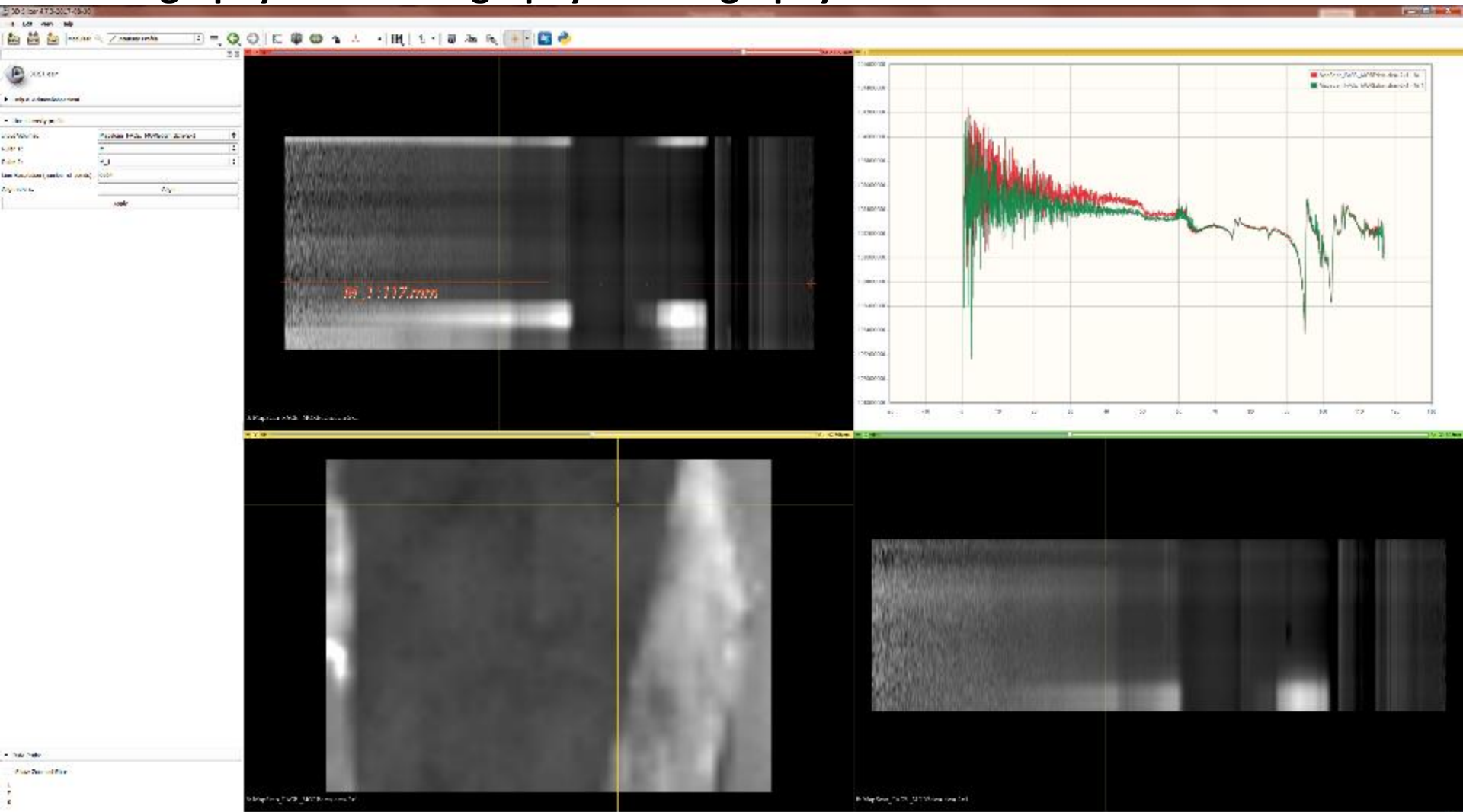
Tomography ... “i” Tomography - iTomography



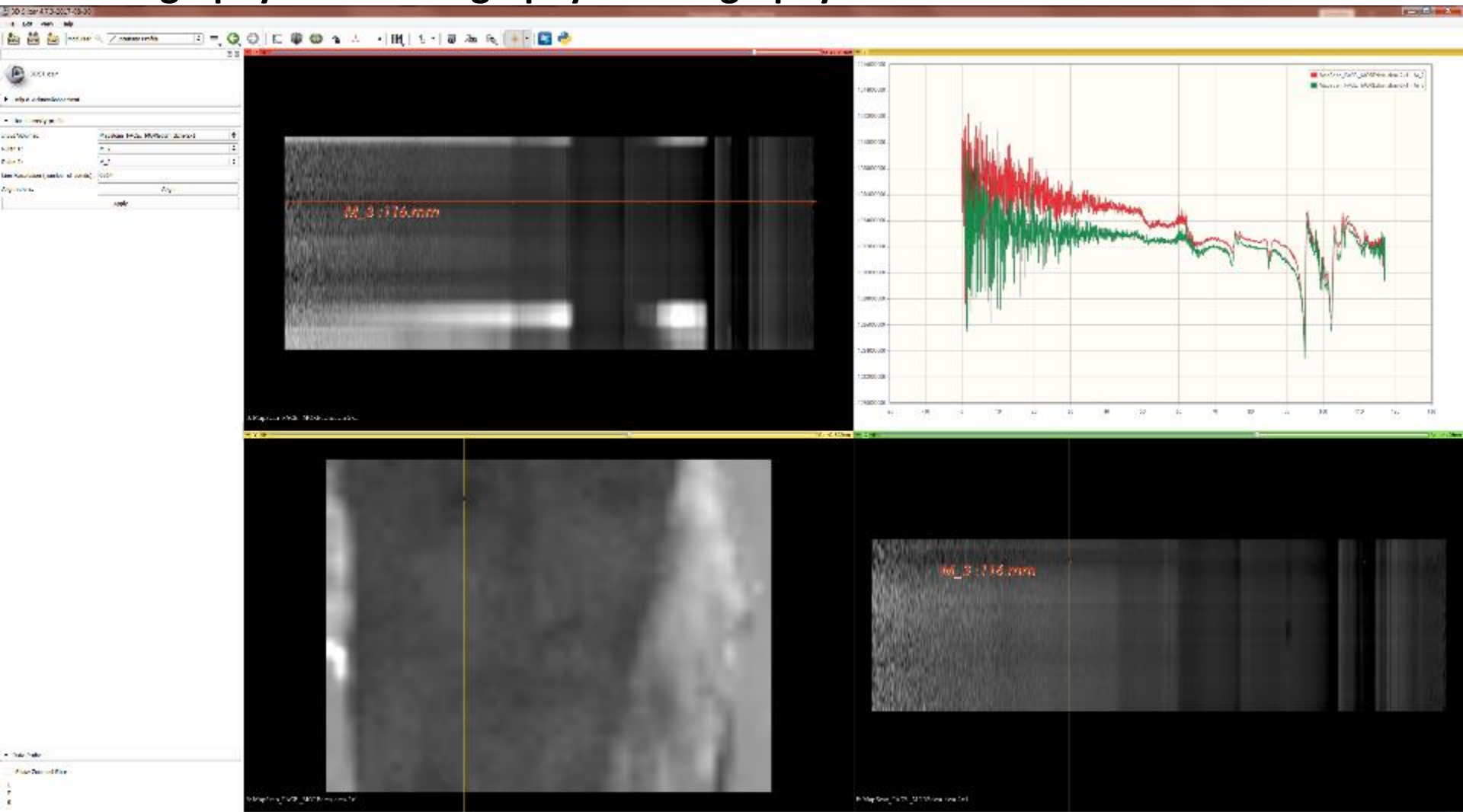
Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



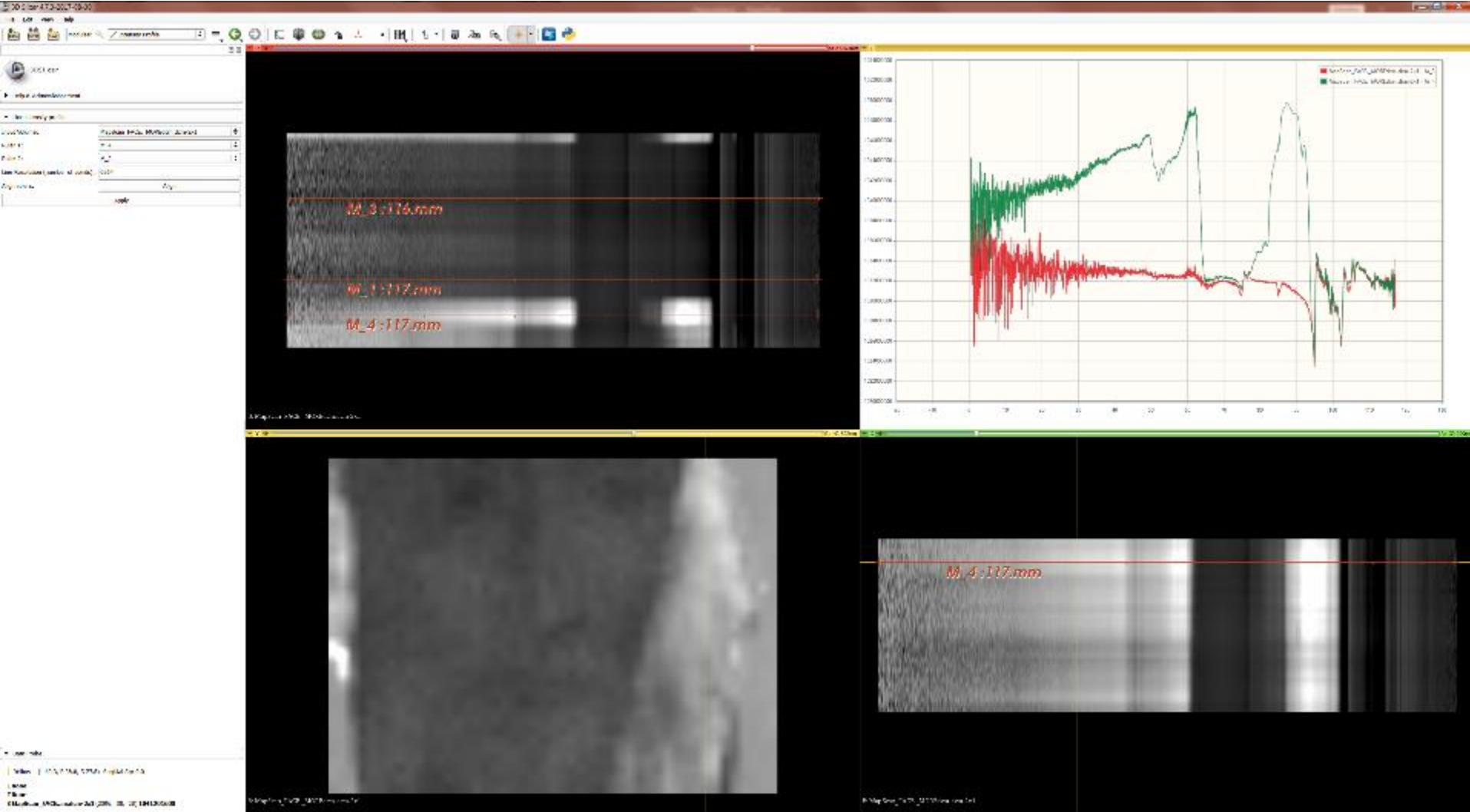
Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



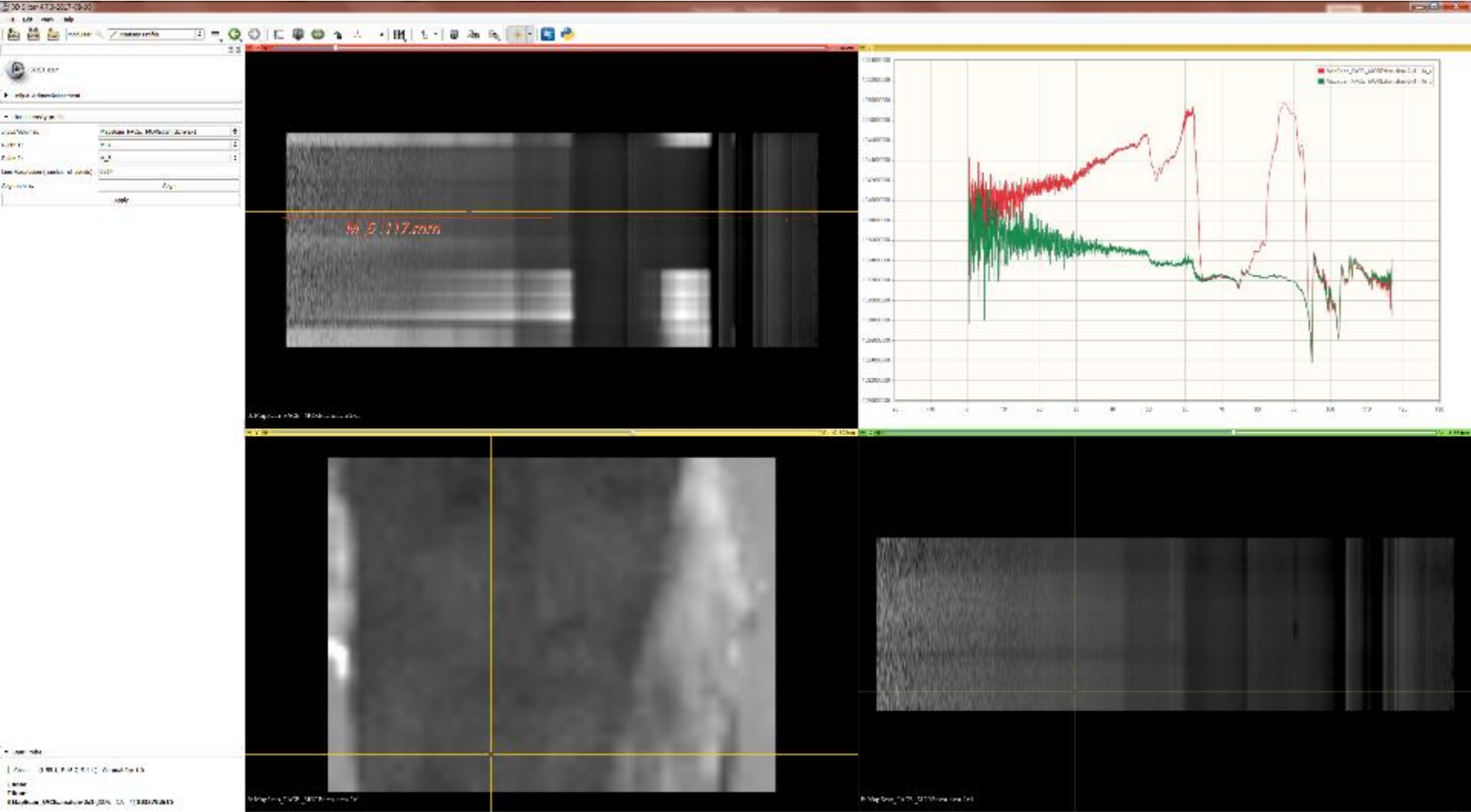
Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



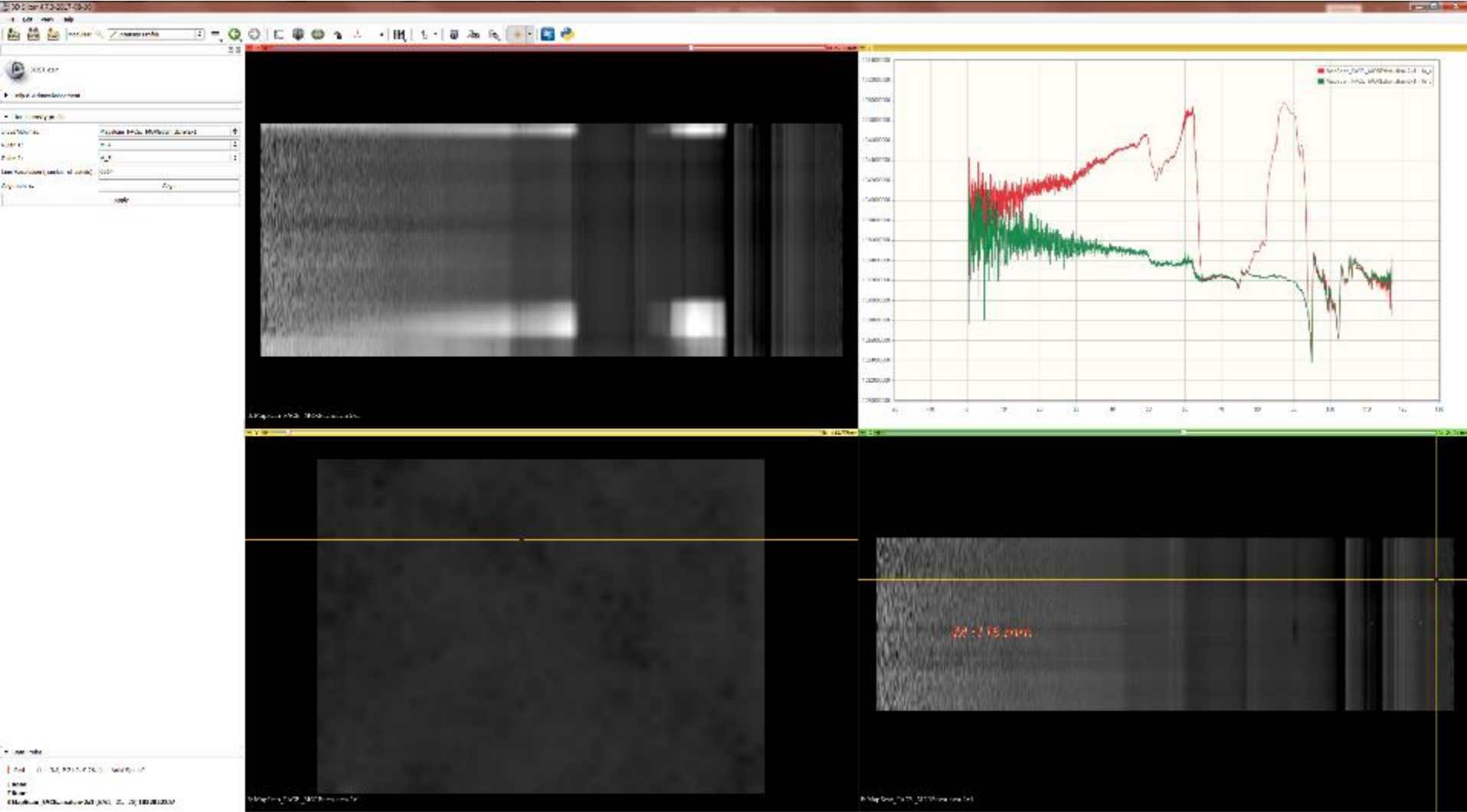
Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



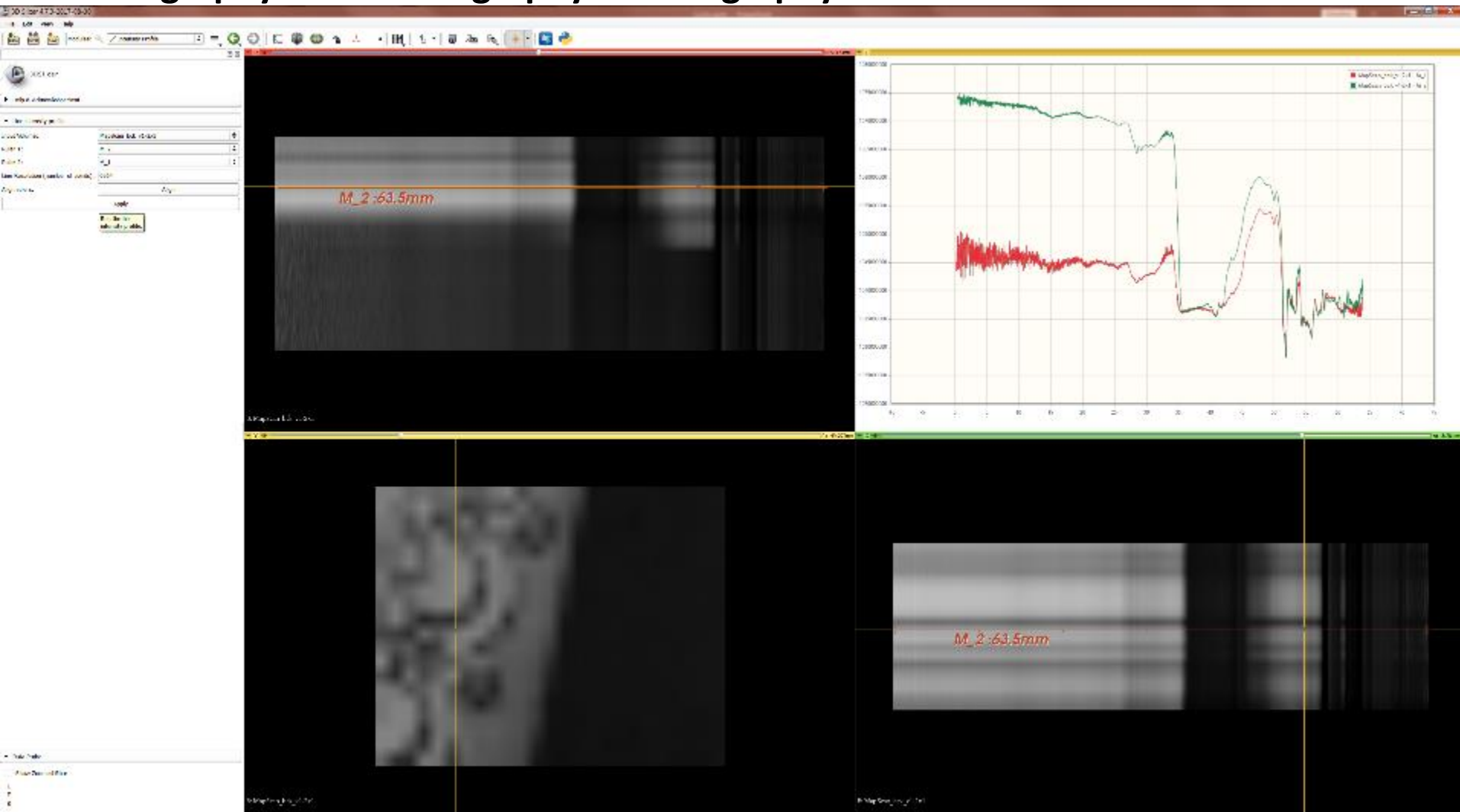
Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... “i” Tomography - iTomography



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography





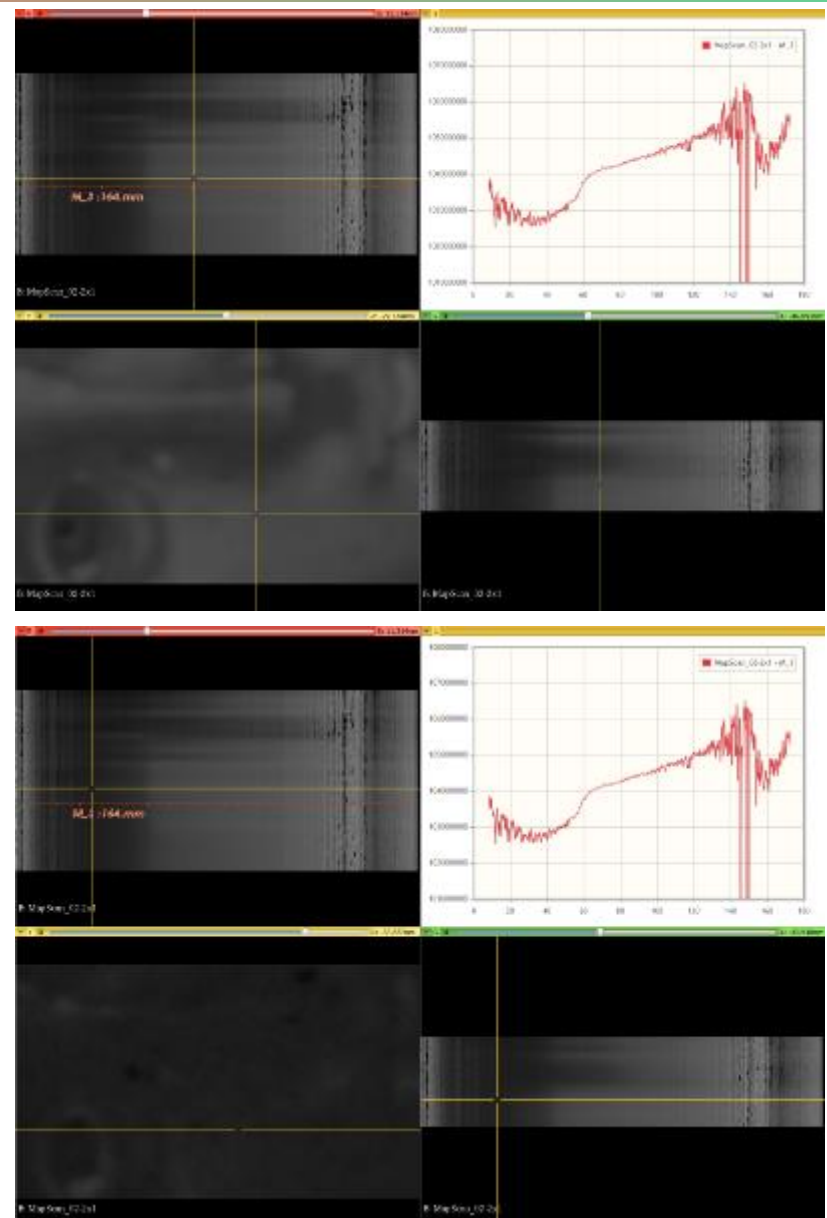
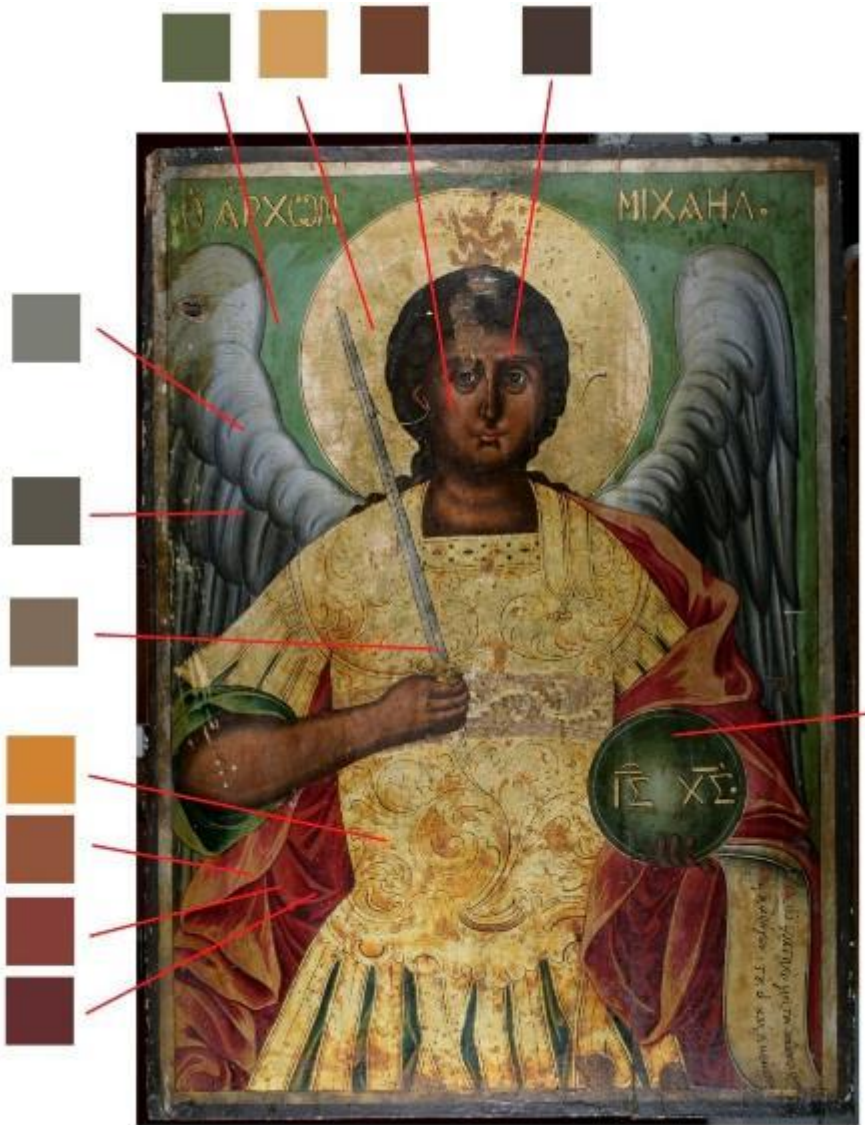
Combination/ Fusion of the data –
(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)
Tomography ... “i” Tomography - iTomography

UV/Vis measurements



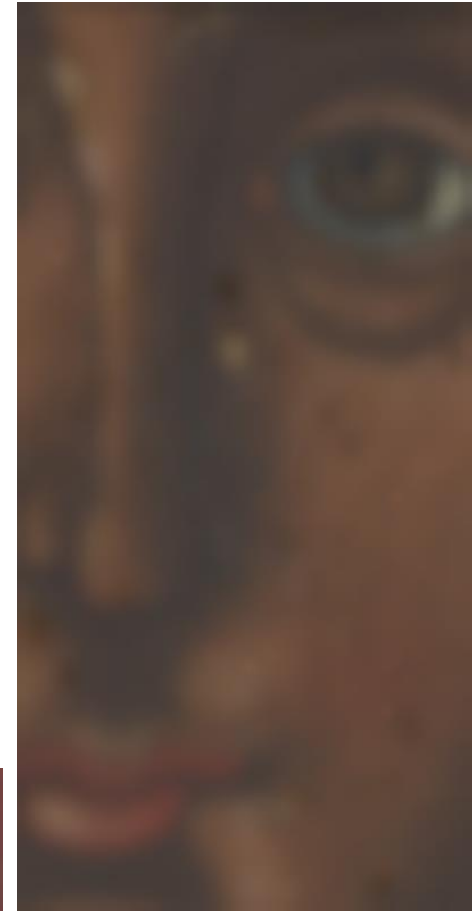


Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography





Archangel Michael



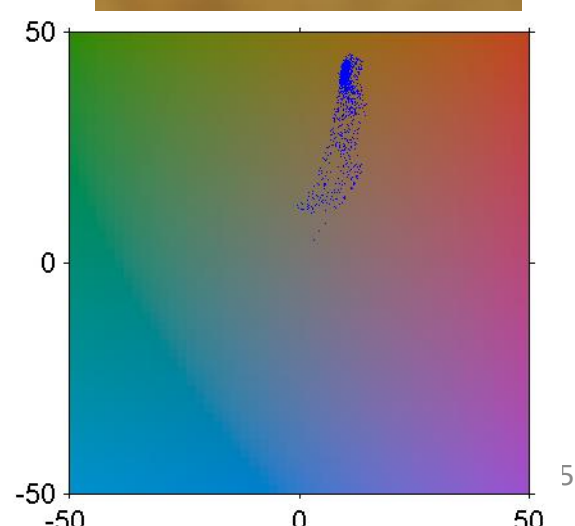
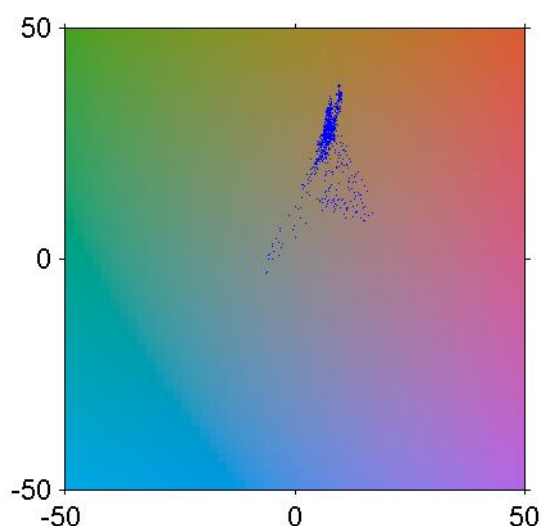
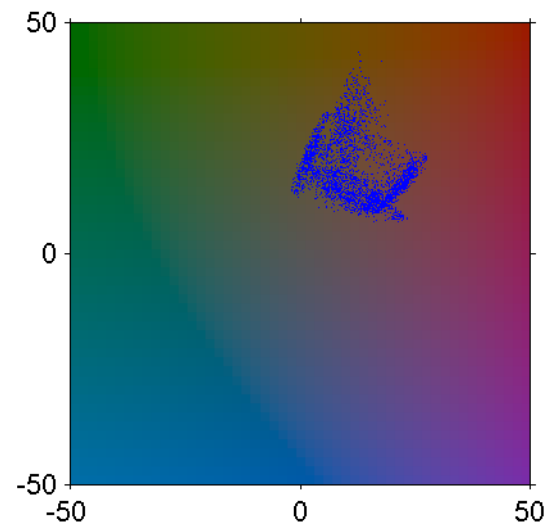
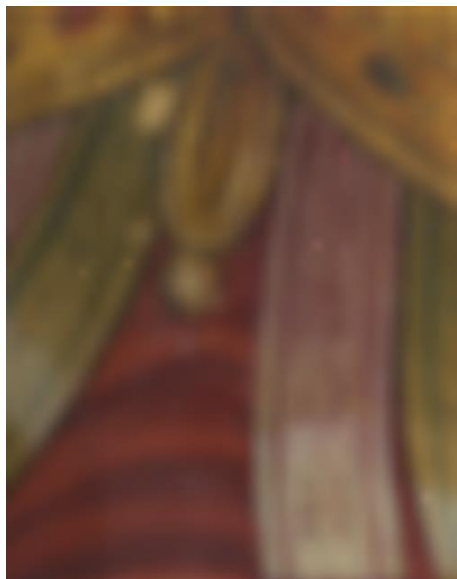


Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... "i" Tomography - iTomography

St. Demetrius



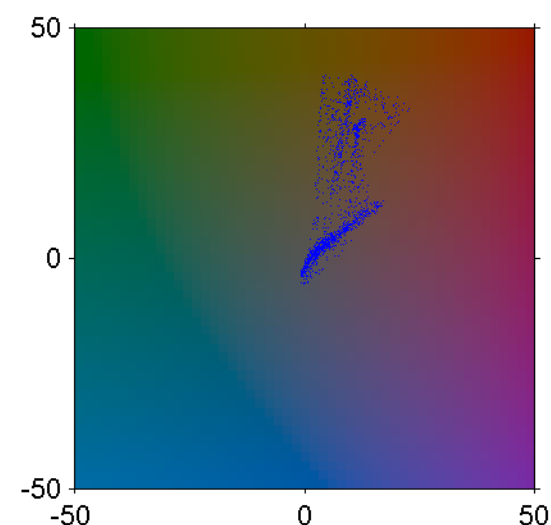
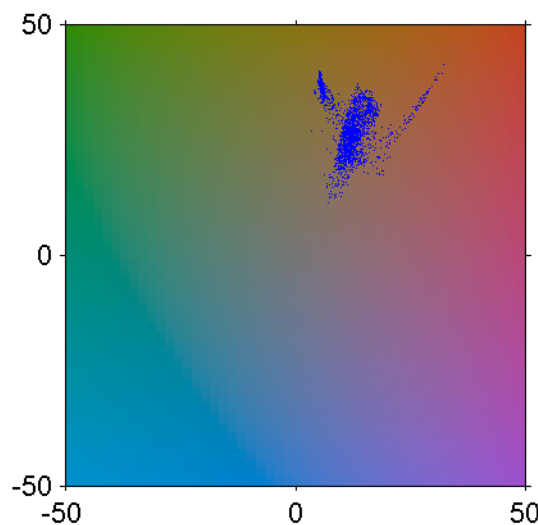
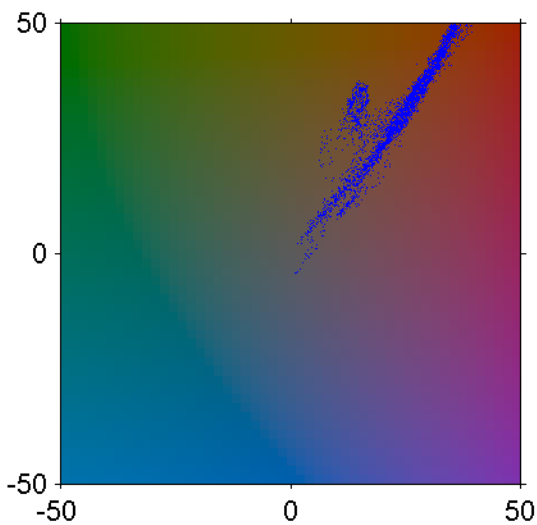
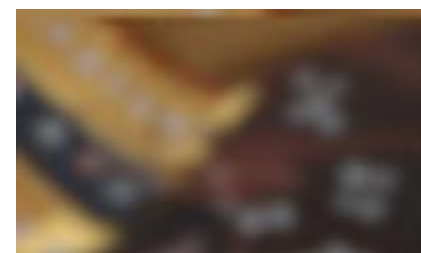


Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... “i” Tomography - iTomography

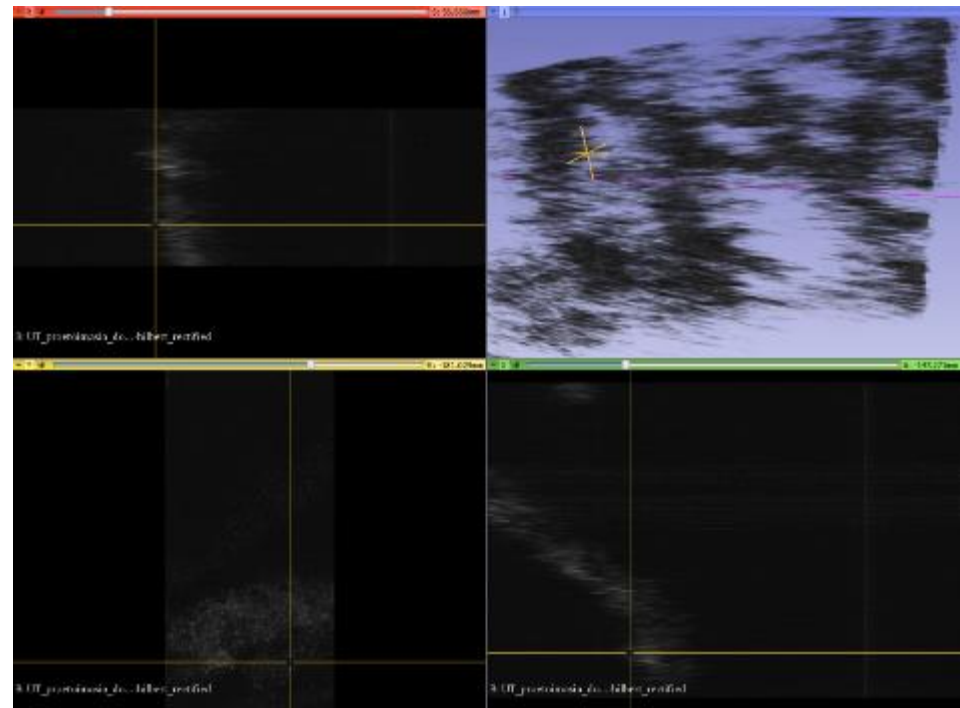
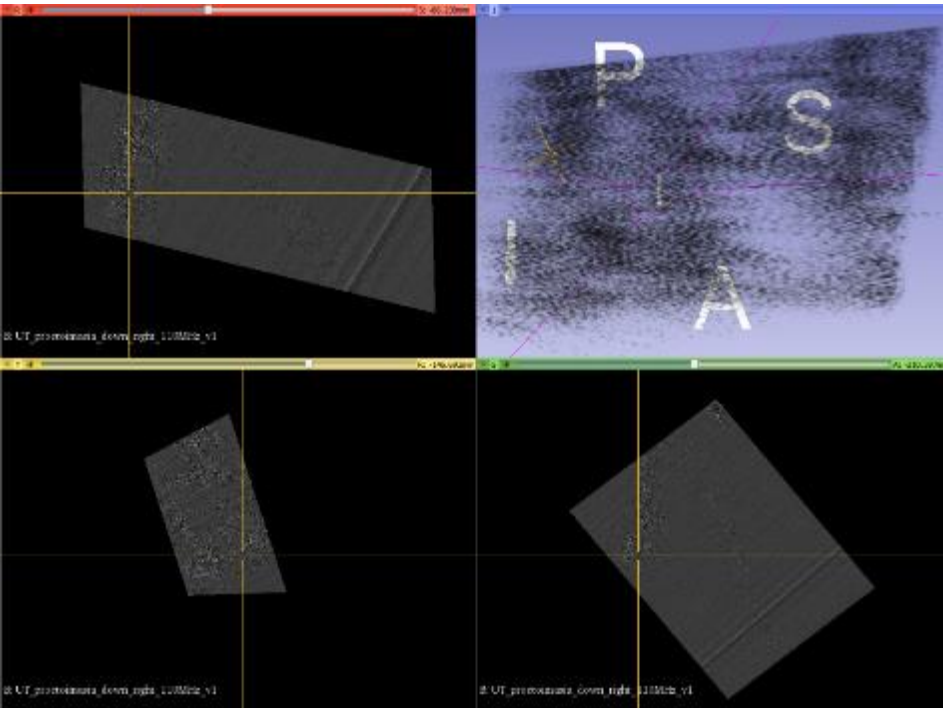
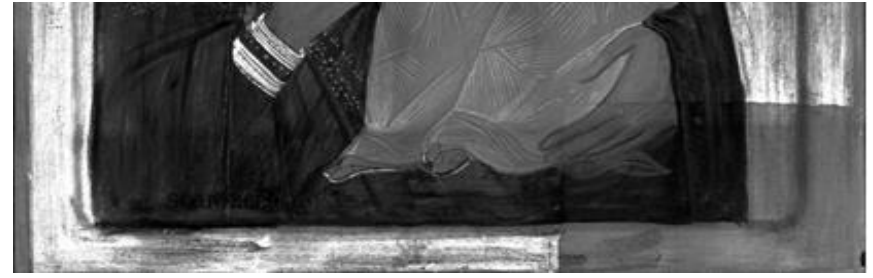
Mother of God





Combination/ Fusion of the data –
(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)
Tomography ... “i” Tomography - iTomography

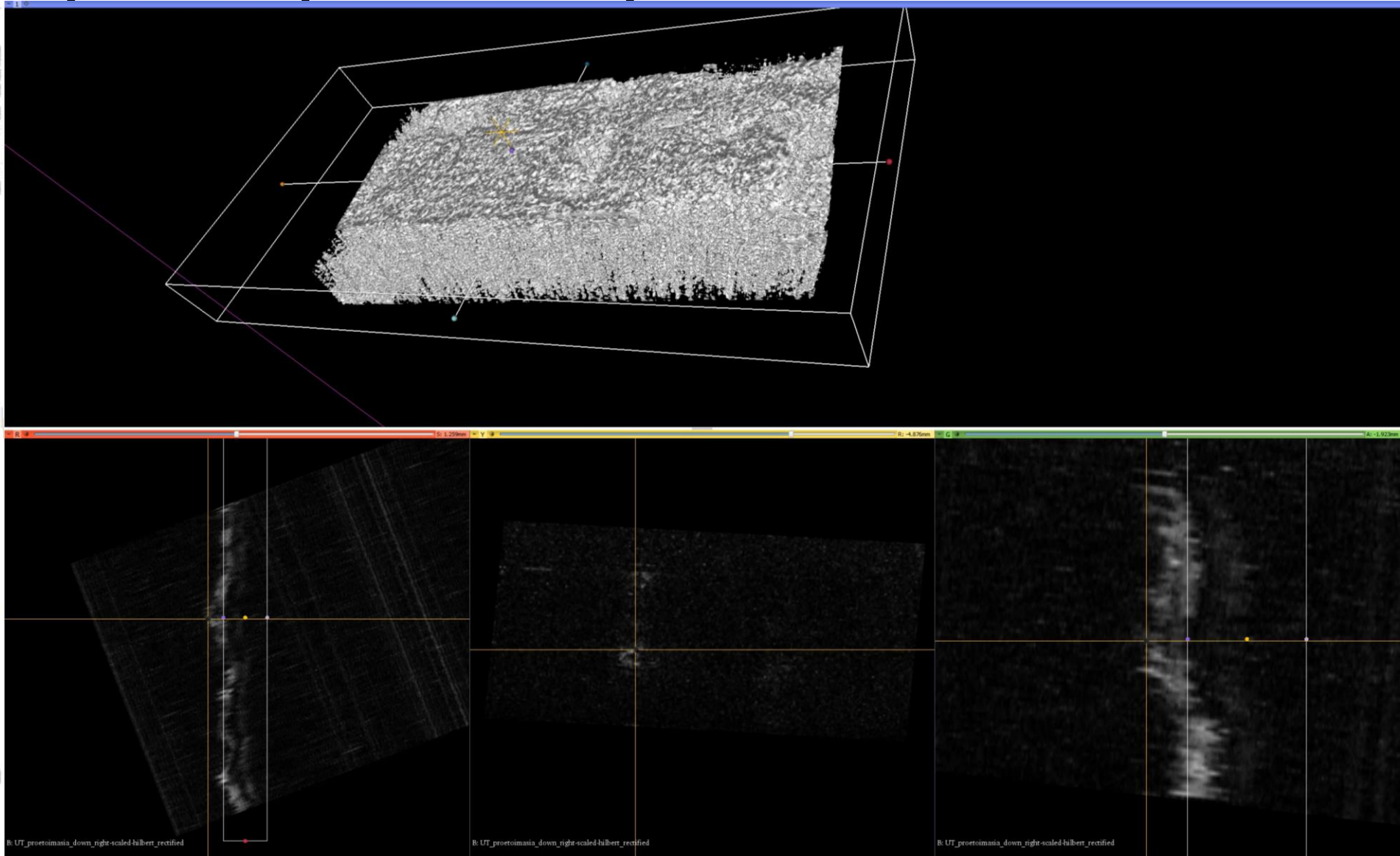
Ultrasound μ Tomography



Hilbert transform is applied



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



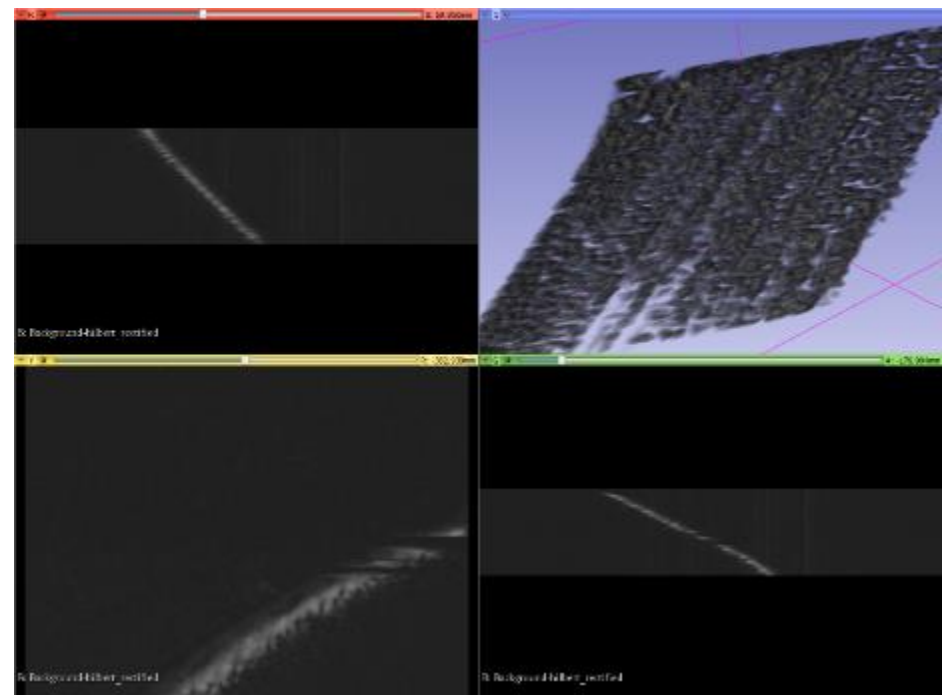
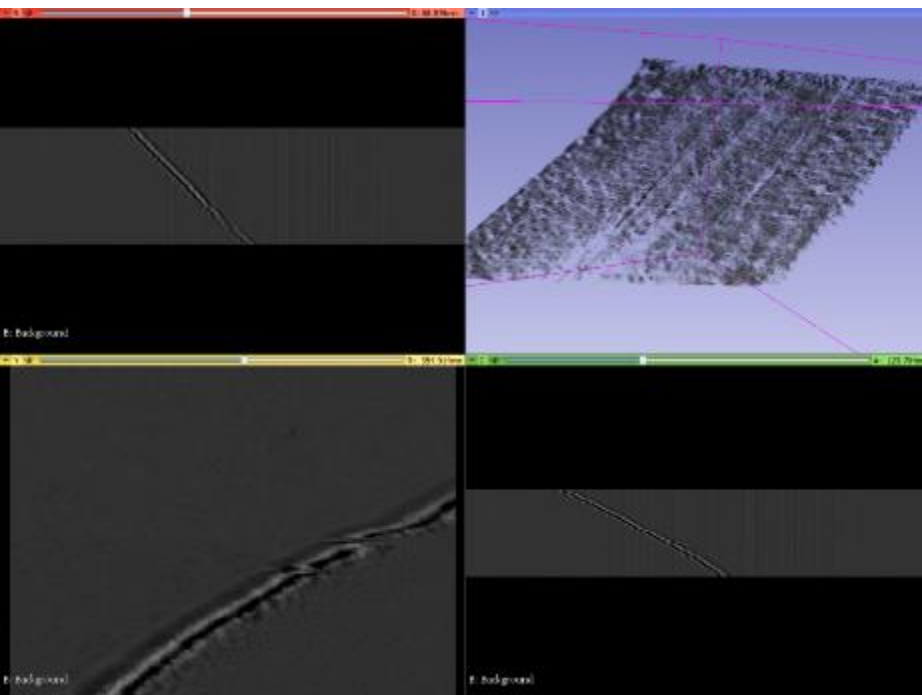


Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... “i” Tomography - iTomography

Ultrasound



Hilbert transform is applied

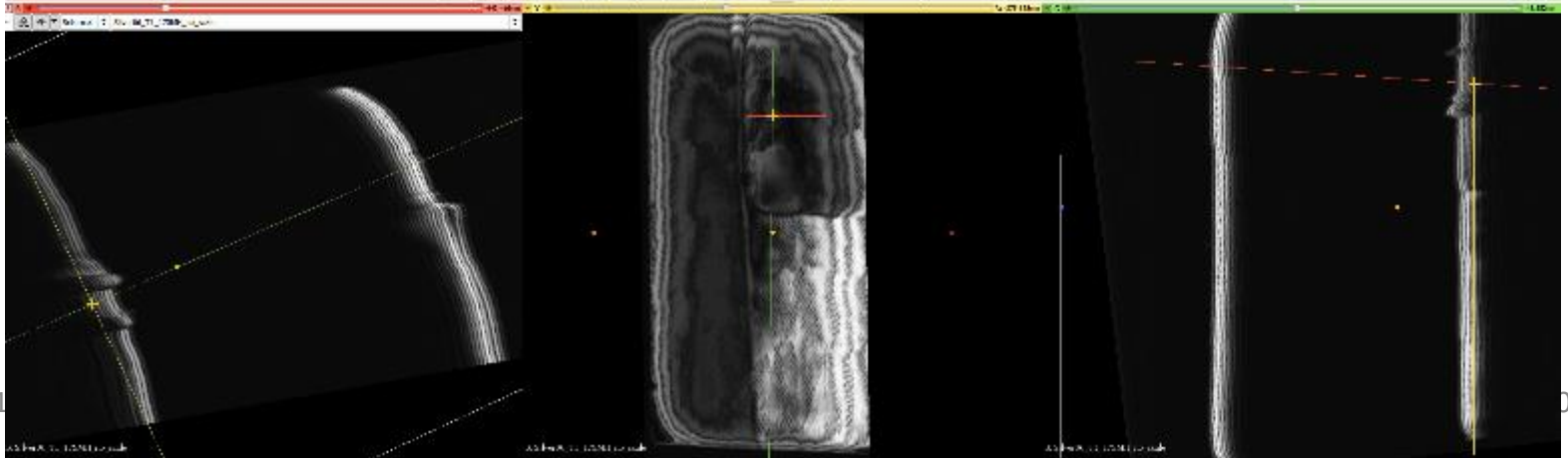
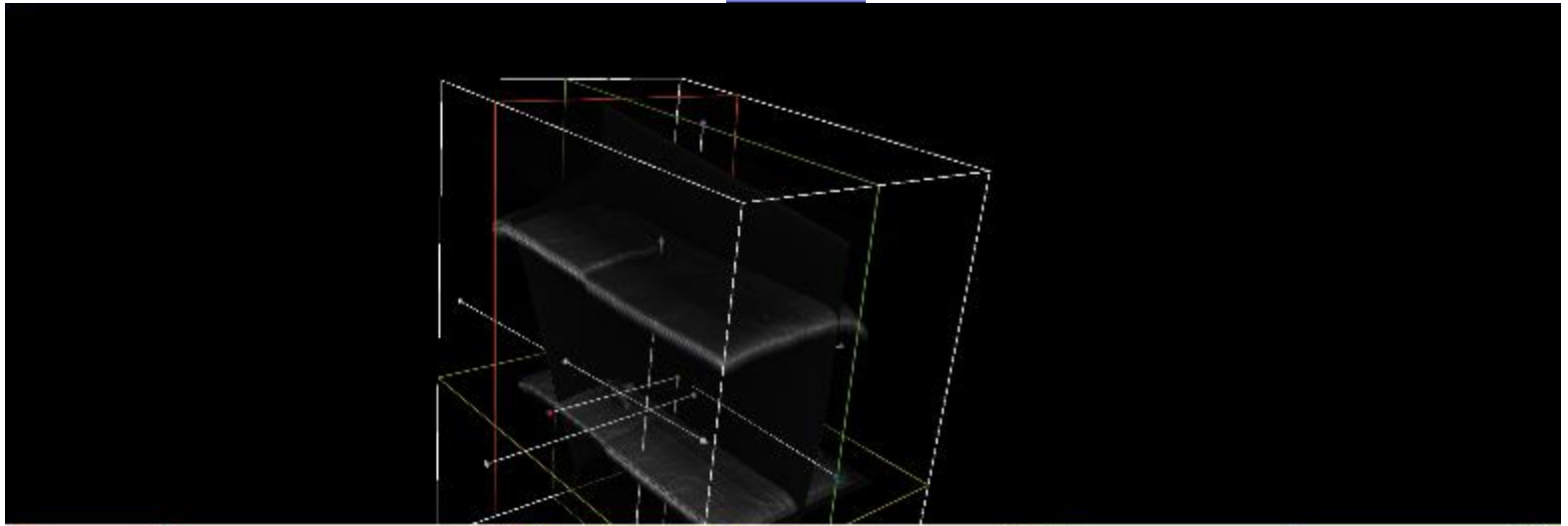
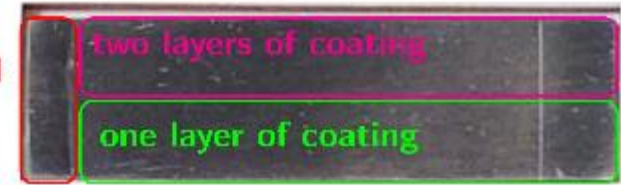


Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography

uncoated
area



uncoated
area



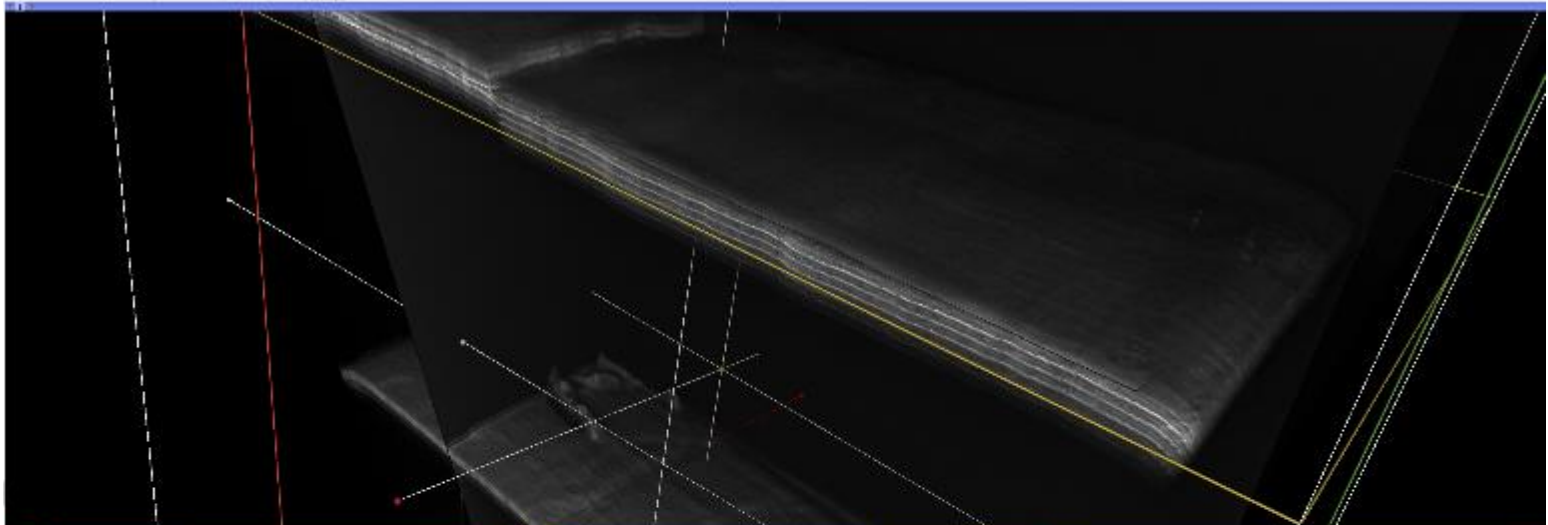
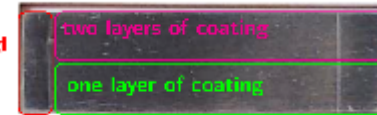


Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography

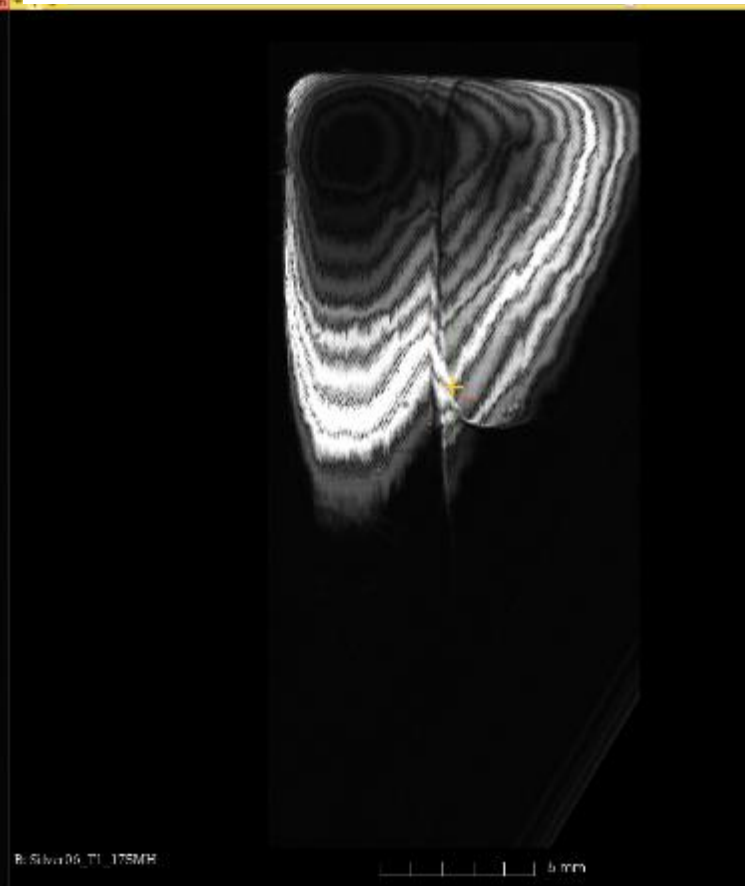
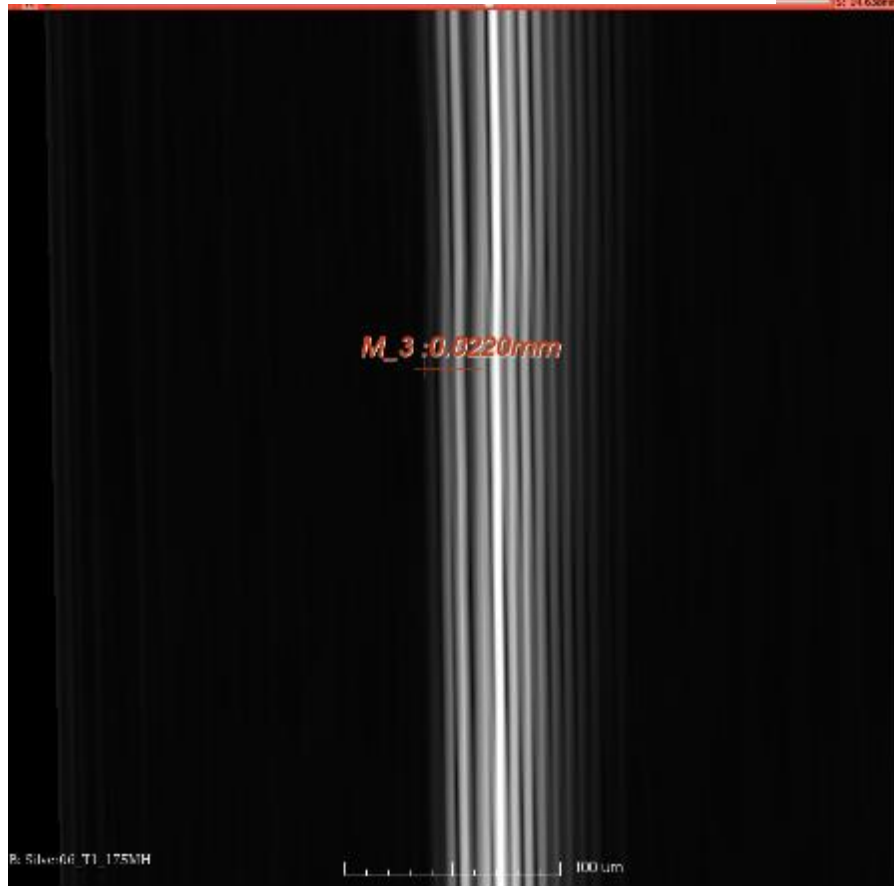
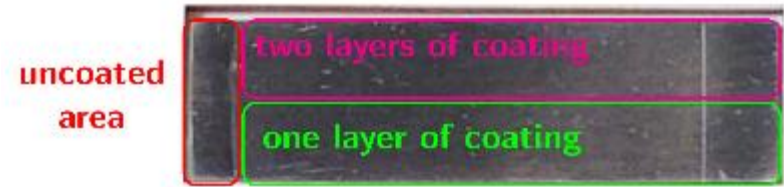
uncoated
area



uncoated
area



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography

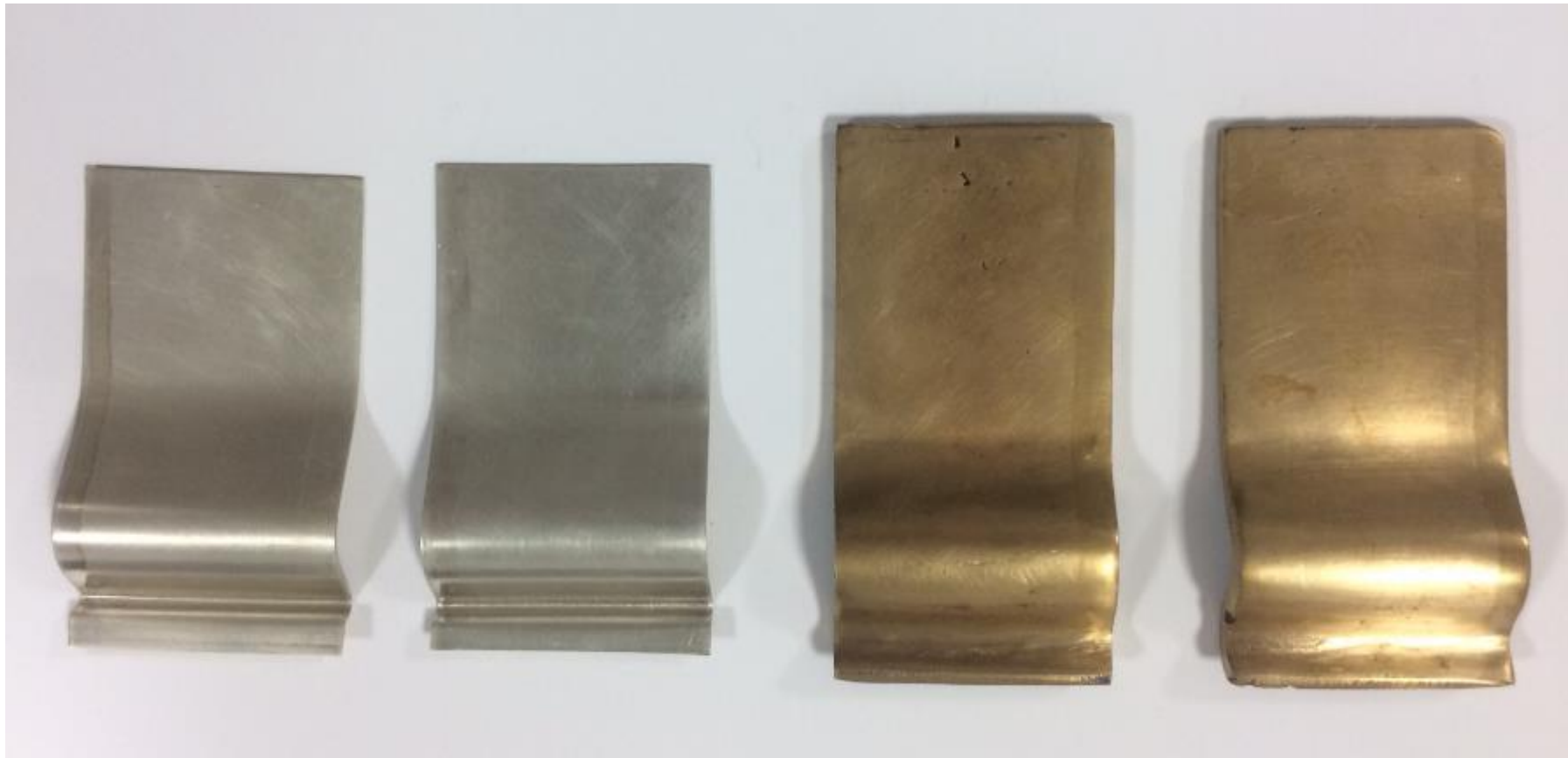


Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... “i” Tomography - iTomography

silver, bronze, iron



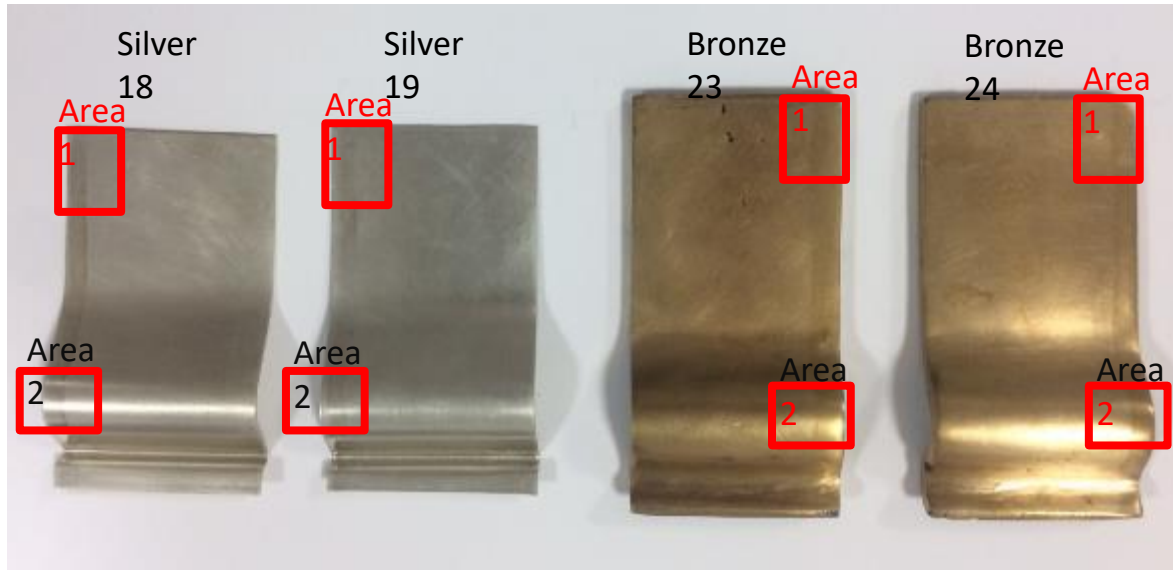


Combination/ Fusion of the data –

(IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...)

Tomography ... “i” Tomography - iTomography

Thickness Measurement of Homogeneous Materials



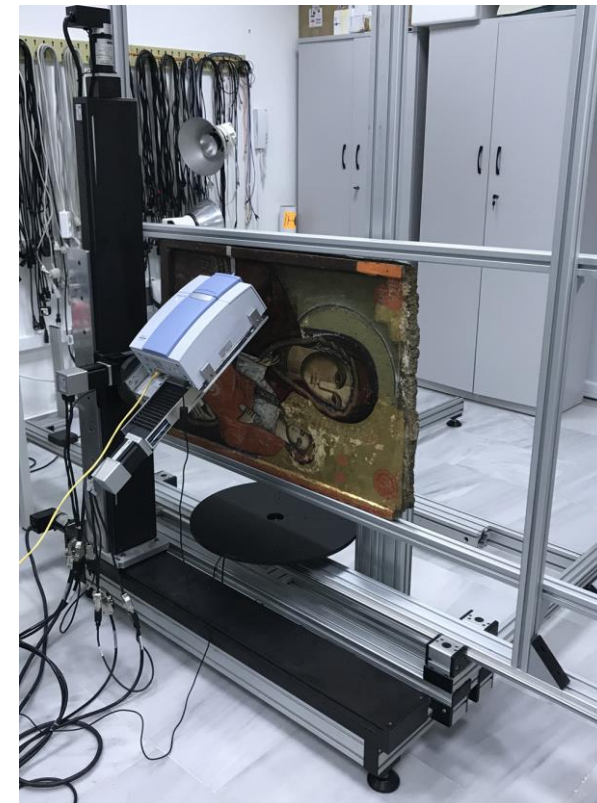
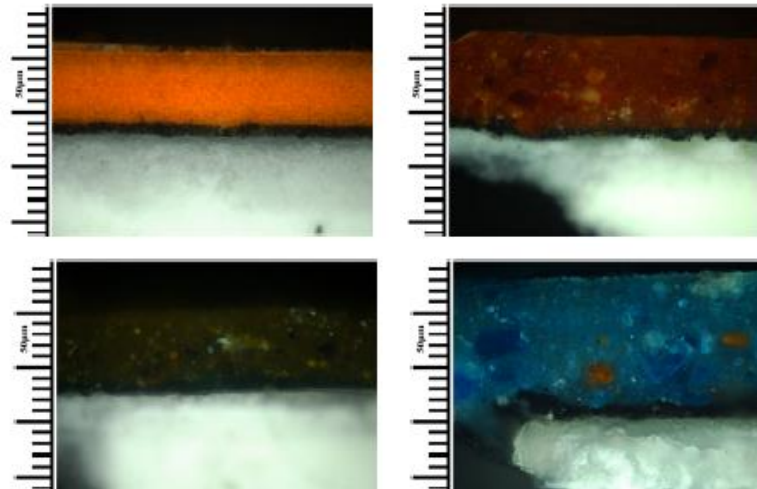
Dimensions

Area 1: 10 x 10mm

Area 2: 10 x 3 mm

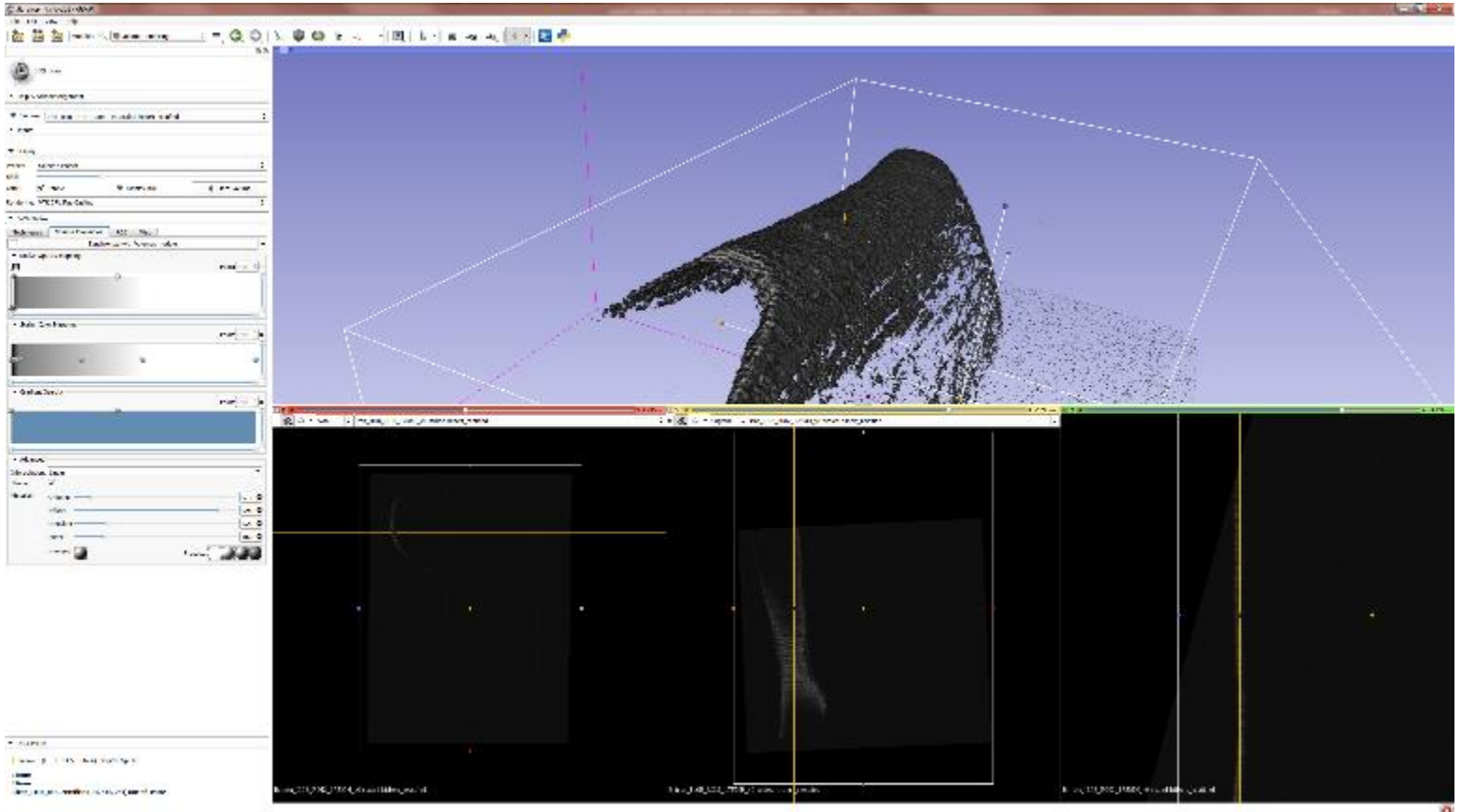
Varnishes

- Nitrocellulose
- INCRAL



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography

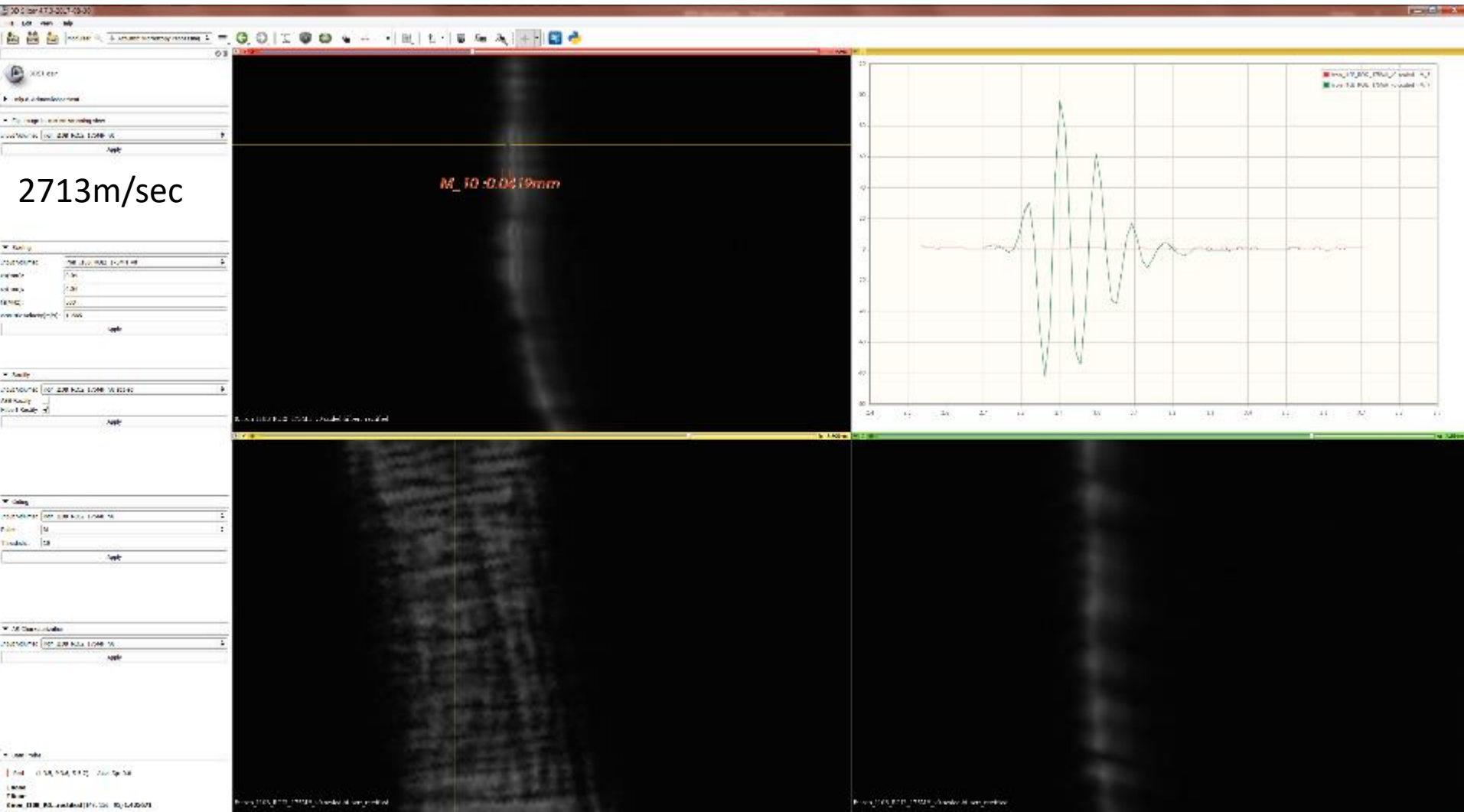
IRON I10B



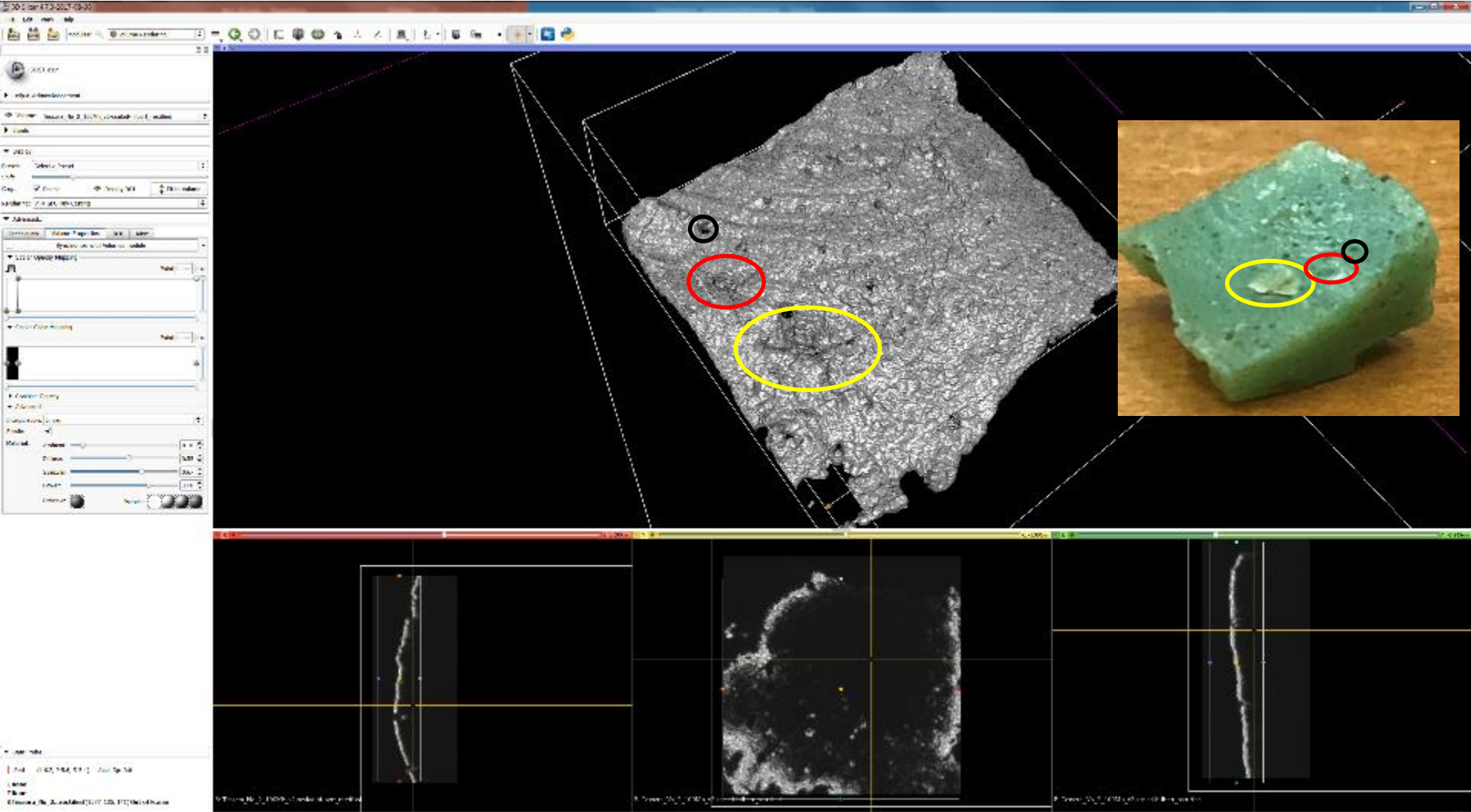
Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography

Iron 10

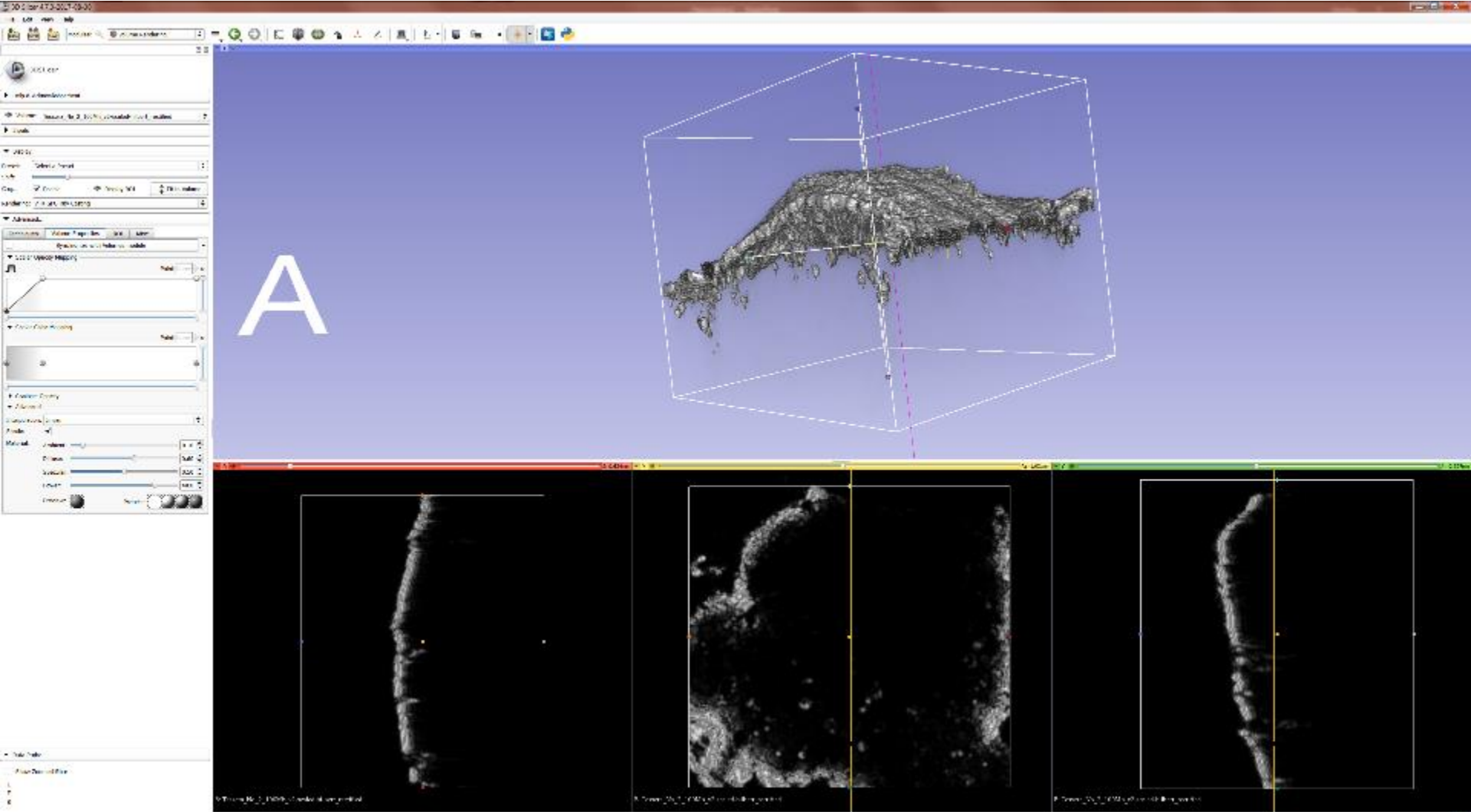
Ultrasonic μ tomography



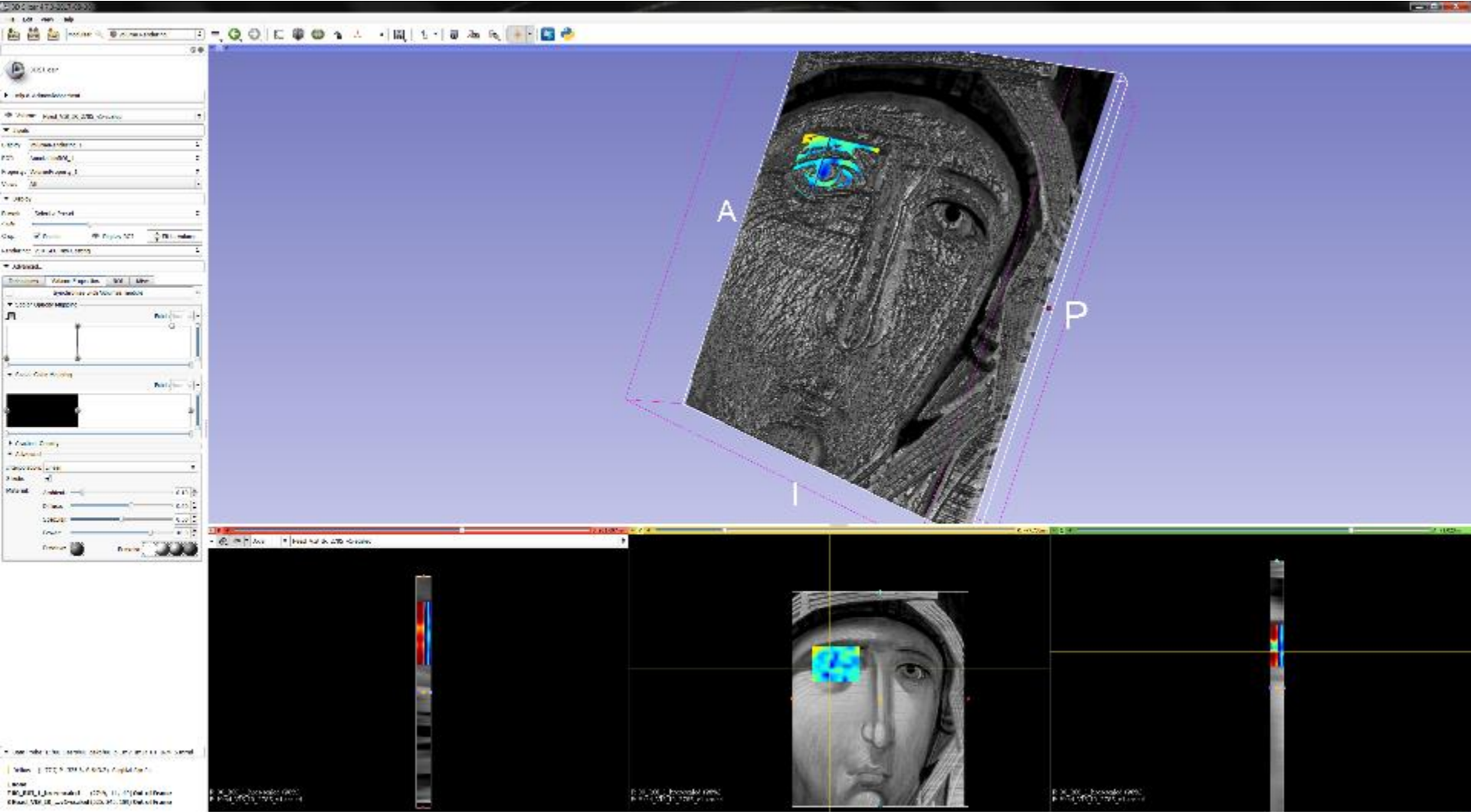
Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography

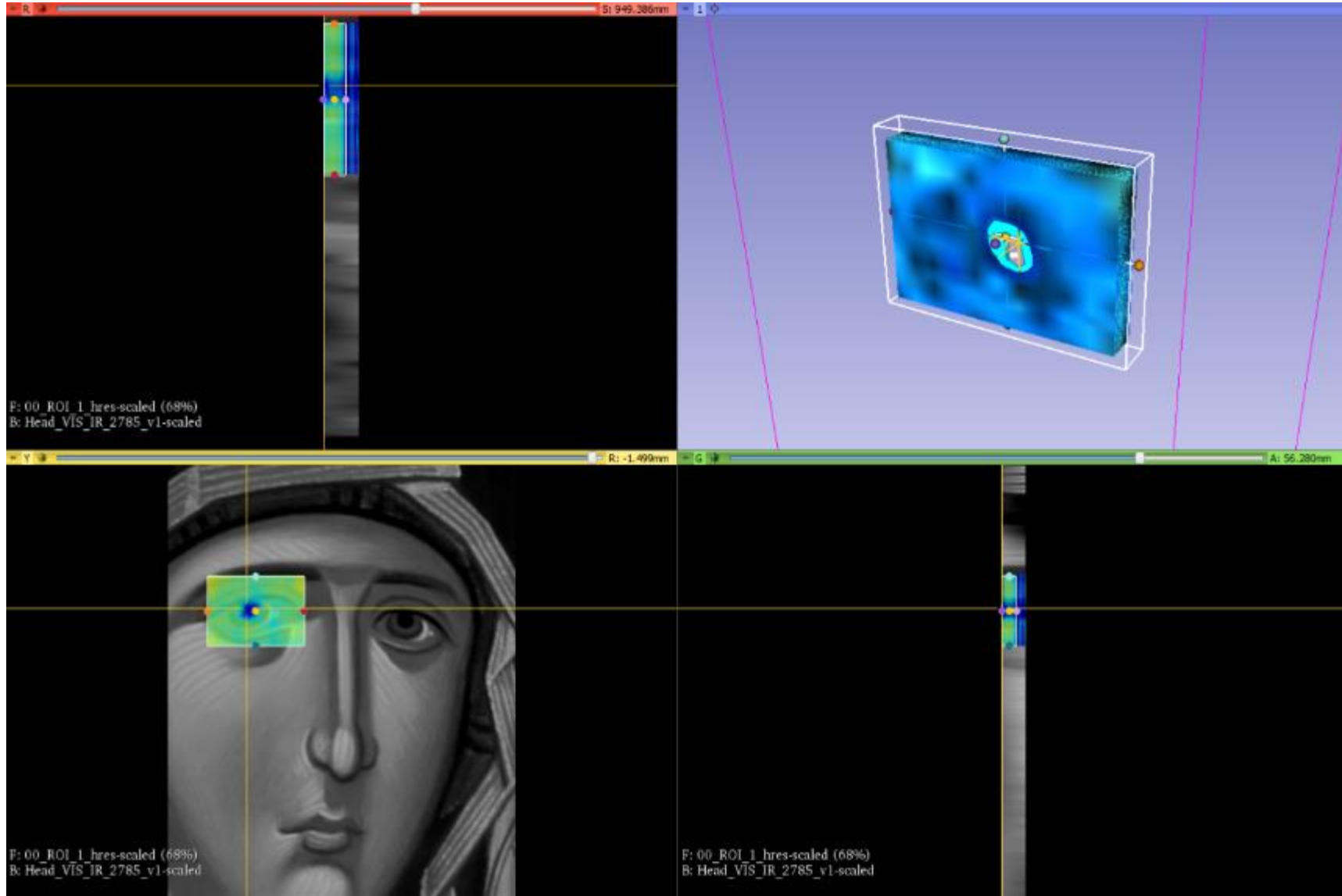


Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography

Infrared mapping spectroscopy
Infrared imaging 1.5-26μm



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography

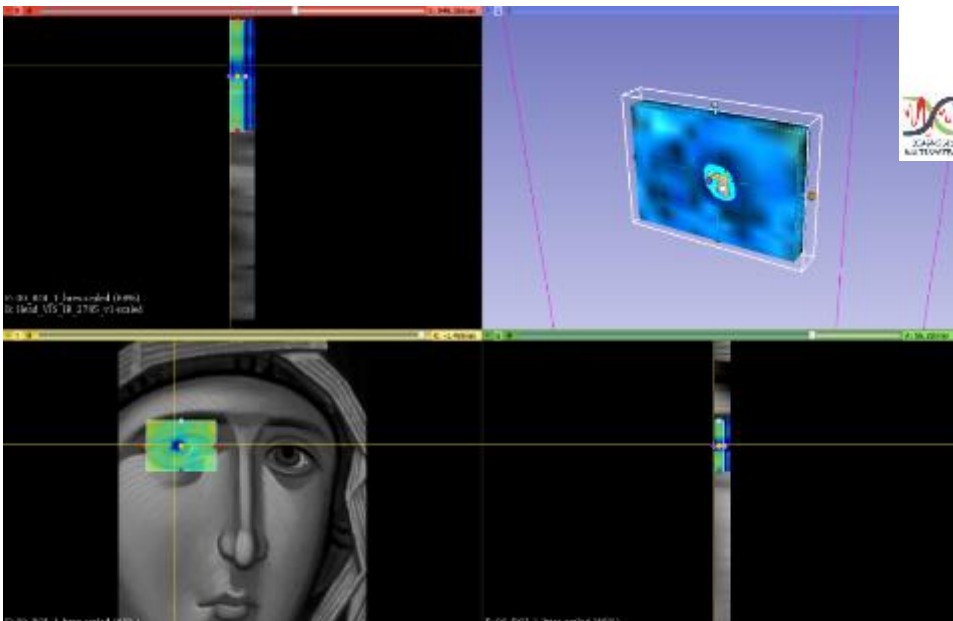
Infrared mapping spectroscopy,
hyperspectral mapping imaging
from 1.3-26 μm
Infrared imaging 1.5-5 μm

IPERION CH 6.2 Advanced mobile instruments for coupling point analytical and imaging methods

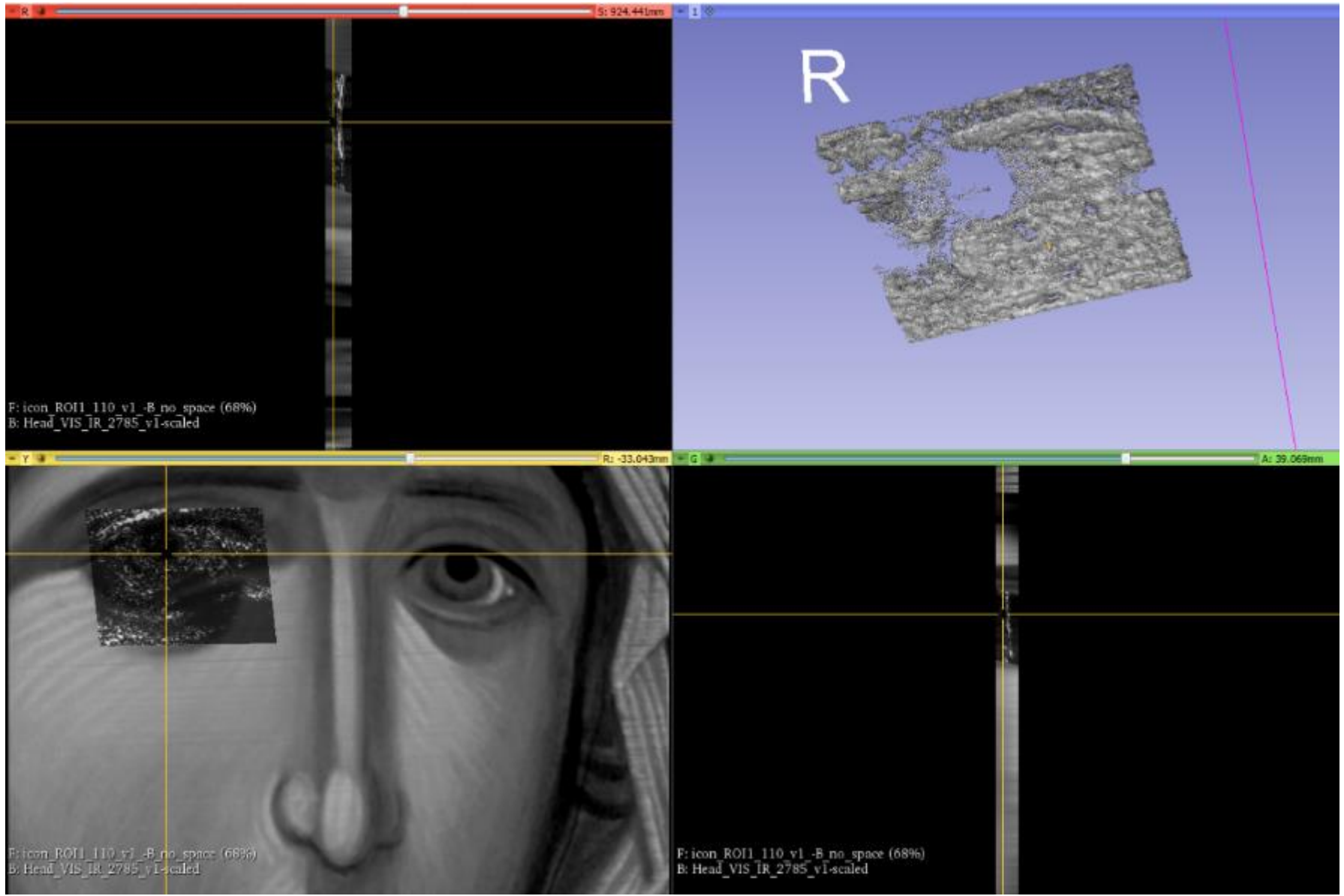
Infrared imaging 1.5-5 μm
XENICS XMID InSb 1-5 μm

Infrared imaging 8-14 μm
FLIR i60

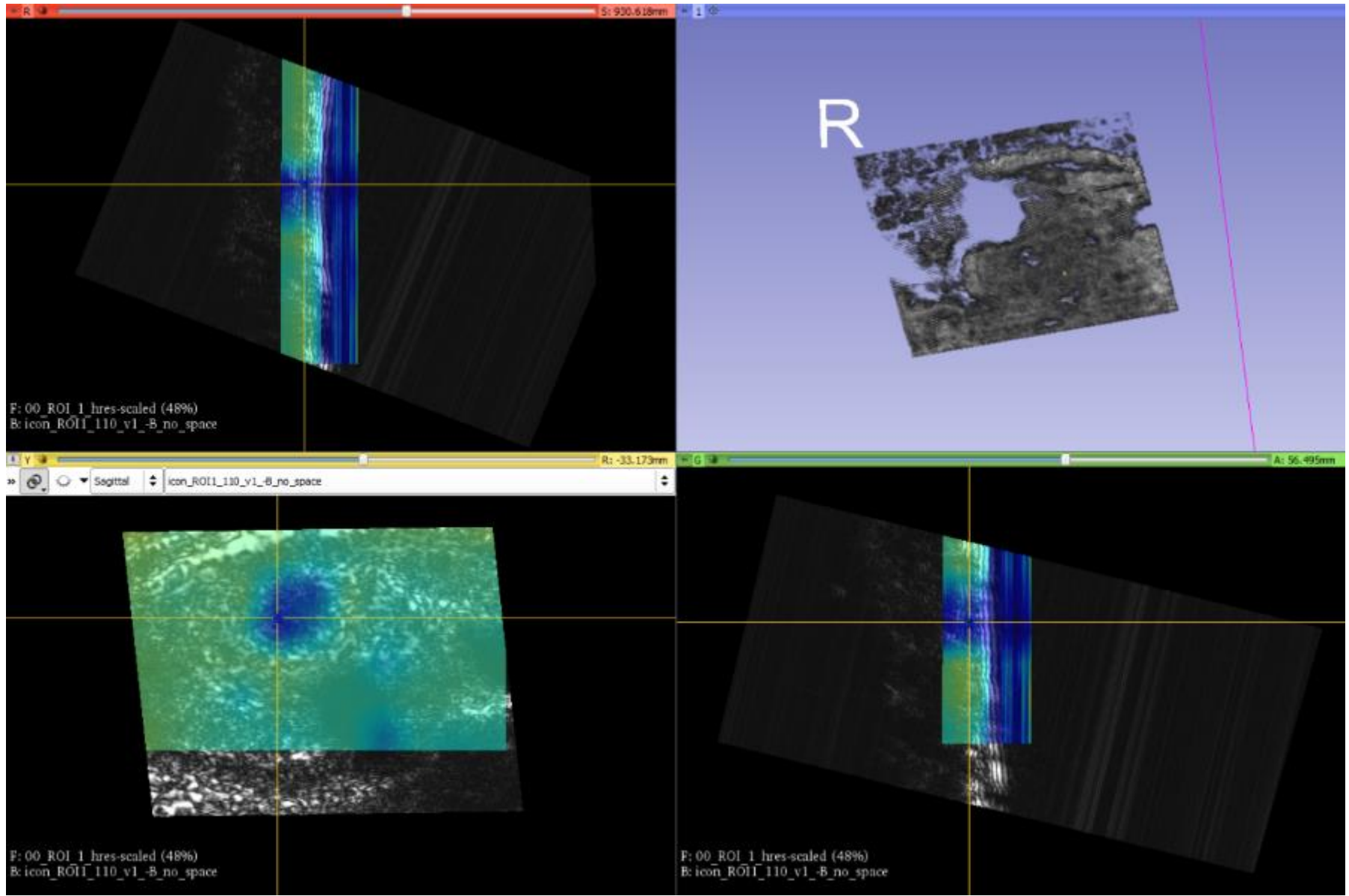
20th, 2018 Copenhagen



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



Combination/ Fusion of the data – (IR Spectroscopic mapping, Infrared Imaging, Ultrasonic tomography, UV-VIS, ...) Tomography ... “i” Tomography - iTomography



“i” Tomography – iTomography - eTomography